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# **Roboy Dialog Manager**

***Release 0.0.***

**Jul 04, 2018**



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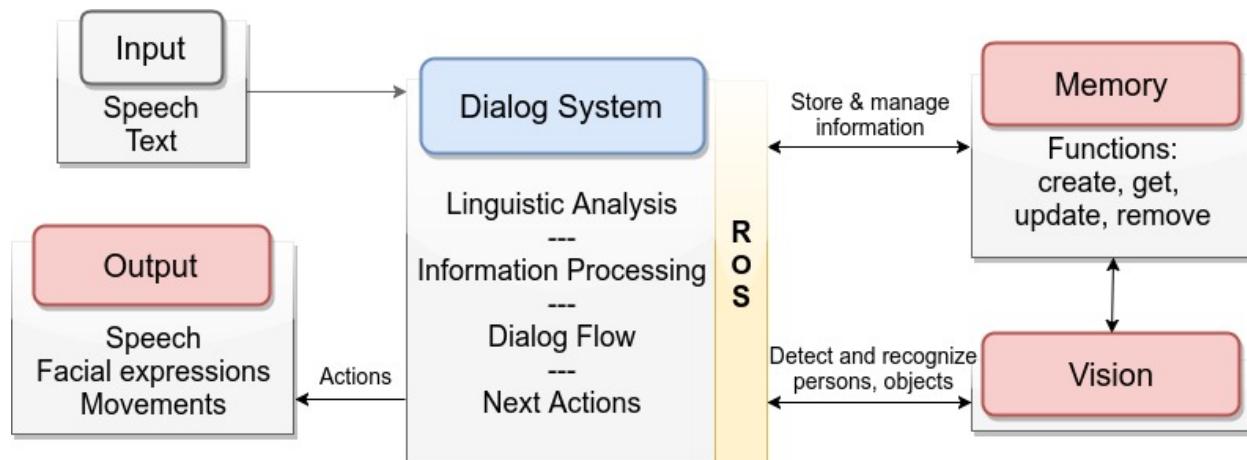
## Usage and Installation

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This project aims to implement human-like conversation routines for the humanoid anthropomimetic robot Roboy. The overview diagram shows the external systems which Dialog System interacts with, and the tasks for which the system is responsible.





# CHAPTER 1

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## Status

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Stable functionality:

- Roboy introduces himself
- Roboy answers questions about himself
- Roboy recognizes once someone says his name
- Roboy asks questions people he meets

In development:

- Roboy stores and recalls information (name, occupation, ect.) about people he meets
- Roboy recognizes the intent behind an asked questions (age, creator, capabilities etc.)



# CHAPTER 2

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Contents:

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## 2.1 Installation

We use Apache Maven build automation tool.

### 2.1.1 Using command line

Install Maven on the computer. `sudo apt install maven`

Clone the Dialog Manager repository. `git clone https://github.com/Roboy/DialogSystem`

Navigate to the root module. `cd DialogSystem`

Compile the project - Maven will take care of the rest. `mvn compile`

Execute the project. `mvn exec:java -Dexec.mainClass="roboy.dialog.DialogSystem"`

### 2.1.2 Using IDE (Eclipse, IntelliJ IDEA)

Clone the Dialog Manager repository. `git clone https://github.com/Roboy/DialogSystem`

Now, import Dialog System as a Maven project into the IDE of your choice. Build and execute using `roboy.dialog.DialogSystem` as the main class.

## 2.2 Getting started

### 2.2.1 How does it work?

The basic NLP architecture is designed as a pipeline.

1. An input device (derived from `de.roboy.io.InputDevice`) is producing text.

2. The text is passed to a variety of linguistic analyzers (derived from `de.roboy.linguistics.sentenceanalysis.Analyzer`). This currently consists of a Tokenizer and a POS tagger (both in `de.roboy.linguistics.sentenceanalysis.SentenceAnalyzer`) but could in the future be accompanied by named entity recognition, a syntactical and semantical analysis, an interpretation of the sentence type or other tools.
3. The results of all these linguistics analyzers are collected together with the original text and stored in an Interpretation instance. (`de.roboy.linguistics.sentenceanalysis.Interpretation`)
4. The interpretation is passed on to a state machine (states are derived from `de.roboy.dialog.personality.states.State`) within a personality class (derived from `de.roboy.dialog.personality.Personality`) that decides how to react to the utterance. In the future, the intentions (`de.roboy.logic.Intention`) determined by the state machine will then be formulated into proper sentences or other actions (`de.roboy.dialog.action.Action`) by a module called Verbalizer. Currently, these actions are still directly created in the personality class.
5. Finally, the created actions are sent to the corresponding output device (`de.roboy.io.OutputDevice`).

## 2.2.2 Design choices

There are interfaces for each step in the processing pipeline to enable an easy exchange of elements. The goal would be to easily exchange personalities based on the occasion.

The implementation of the pipeline is in Java. Integrations with tools in other languages, like C++ RealSense stuff, should be wrapped in a module in the pipeline.

## 2.2.3 How to extend it?

Pick the corresponding interface, depending on which part of the system you want to extend. If you want to add new devices go for the input or output device interfaces. If you want to extend the linguistic analysis implement the Analyzer interface or extend the SentenceAnalyzer class. If you are happy with input, linguistics and output and just want to create more dialog, implement the Personality interface.

Create a new ...	By implementing ...
Input Device	<code>de.roboy.io.InputDevice</code>
NLP Analyzer	<code>de.roboy.linguistics.sentenceanalysis.Analyzer</code>
State Machine	<code>de.roboy.dialog.personality.Personality</code>
State	<code>de.roboy.dialog.personality.states.State</code>
Action type	<code>de.roboy.dialog.action.Action</code>
Output device	<code>de.roboy.io.OutputDevice</code>

The interfaces are deliberately simple, containing only 0 - 2 methods that have to be implemented. Once you implemented your new classes include them in the personality used in `de.roboy.dialog.DialogSystem`, if you only implemented single states or directly in `de.roboy.dialog.DialogSystem` for everything else.

## 2.3 Personality and states

### 2.3.1 Overview

To enable a natural way of communication, Roboy's Dialog Module implements a flexible architecture using personality classes, which each manage a number of different states. This enables us to dynamically react to clues from the

conversation partner and spontaneously switch between purposes and stages of a dialog, mimicing a natural conversation.

### 2.3.2 Personality

During one run-through, the Dialog System uses a single Personality instance (`de.roboy.dialog.personality.Personality`). A personality is designed to define how Roboy reacts to every given situation, and as such Roboy can always only represent one personality at a time. Different personalities are meant to be used in different situations, like a more formal or loose one depending on the occasion.

The current primary personality is the SmallTalkPersonality (`de.roboy.dialog.personality.SmallTalkPersonality`).

A new personality (`roboy.newDialog.StateBasedPersonality`) is currently being implemented. Similarly to the SmallTalkPersonality, it is built on top of a state machine. The new personality is designed to be more generic one and allows to load the behaviour from a personality file. The file stores a representation of the state machine. Additionally, it is still possible to define the dialog structure directly from code (as it was done in previous implementations).

### 2.3.3 Legacy State

A state's activity can be divided into two stages. When the state is entered, the initial action from the `act()` method is carried out, which is expected to trigger a response from the person. After Roboy has received and analyzed the response, the `react()` method completes the current state's actions and Roboy moves on to the next state.

The AbstractBooleanState describes a special case where the state's reaction depends on whether the `act()` method resulted in successful interaction. States which implement AbstractBooleanState can respond differently move on into different stages according to their `determineSuccess()` method.

For example, the initial action of `de.roboy.dialog.personality.states.IntroductionState` is to ask the user's name. Then the response is analyzed externally and when the state's `determineSuccess()` method is called, it checks whether a name was extracted. If this is the case, then the system outputs predefined sentences with the extracted name embedded into them. Otherwise, fallback sentences are used which do not include a name.

### 2.3.4 New State

Currently, we are improving the state system. Old state implementations will be replaced with newer ones. The functionality of the AbstractBooleanState will be improved to allow arbitrary conditional transitions in every new state. Nested states will be replaced with the fallback concept.

A state's activity can be divided into two stages. When the state is entered, the initial action from the `act()` method is carried out, which is expected to trigger a response from the person. After Roboy has received and analyzed the response, the `react()` method completes the current state's actions and Roboy picks a transition to the next state defined by the `getNextState()` method of the current state.

It is possible to remain in the same state for many cycles. In this case the `getNextState()` method just returns a reference to the current state (`this`) and the `act()` and `react()` methods are carried out again.

A state can have any number of transitions to other states. Every transition has a name (like "next" or "errorState"). When changing states, the following state can be selected based on internal conditions of the current state. For example, a state can expect a "yes/no" answer and have tree outgoing transitions: "gotYes", "gotNo" and "askAgain" (if the reply is not "yes/no").

When designing a new state, only the transition names are defined. The following states are defined in the personality file later. At run time the state machine loads the file and initializes the transitions to point to correct states. The destination state can be retrieved by the transition name using `getTransition(transitionName)`.

A fallback can be attached to a state. In the case this state doesn't know how to react to an utterance, it can return `null` from the `react()` function. The state machine will query the fallback in this case. This concept helps to decouple the states and reduce the dependencies between them. When implementing the `react()` function of a new state, it is sufficient to detect unknown input and return `null`.

### 2.3.5 Legacy State machine structure

Every state defines at least one successor state, and more complex hierarchies can be realized - for example as a fallback system for cases when a single state cannot respond in a meaningful manner. The fallback system implemented using nested states in the legacy state machine and will be improved in the newer implementation. The following is an example from the documentation of SmallTalkPersonality:

The current legacy state machine looks like this:

#### Greeting state

V

#### Introduction state

V

#### Question Randomizer state

##### |\_Question Answering state

##### |\_Segue state |\_Wild talk state

The Question Randomizer, Question Answering, Segue and Wilk talk states are nested. If one cannot give an appropriate reaction to the given utterance, the utterance is passed on to the next one. The Wild talk state will always answer.

## 2.4 The memory module

### 2.4.1 General design

To remember information about itself and its conversation partners, their hobbies, occupations and origin, a persistent Memory module has been implemented using the Neo4j graph database.

### 2.4.2 Implementation

Roboy's Dialog System interactions with the Memory module are based on ROS messages. The messages are sent using the methods in `de.roboy.ros.RosMainNode`, which implements the four query types based on the specified Memory services:

Method name	Description
CreateMemoryQuery	Creates a node in Memory database
UpdateMemoryQuery	Adds or changes information of an existing node
GetMemoryQuery	Retrieves either one node or an array of IDs
DeleteMemoryQuery	Removes information from or deletes a node
CypherMemoryQuery	For more complex queries (future)

The messages received from Memory are in JSON format. To enable flexible high-level handling of Memory information, two classes were created to incorporate the node structures and logic inside the Dialog System. The `de.roboy.memory.nodes.MemoryNodeModel` contains the labels, properties and relationships in a format which can be directly parsed from and into JSON. For this, Dialog is using the GSON parsing methods which enable direct translation of a JSON String into its respective Java class representation.

Methods such as `getRelation()` or `setProperties()` were implemented to allow intuitive handling of the `MemoryNodeModel` instances. A separate class, `de.roboy.memory.nodes.Interlocutor`, encapsulates a `MemoryNodeModel` and is intended to further ease saving information about the current conversation partner of Roboy. Interlocutor goes one step further by also abstracting the actual calls to memory, such that adding the name of the conversant performs an automatic lookup in the memory with subsequent updating of the person-related information. This is then available in all subsequent interactions, such that Roboy can refrain from asking questions twice, or refer to information he rememberes from earlier conversations.

## 2.5 Configuration

The Dialog Manager can be called with a specific system configuration that determines which external services will be used within the session. The `ROS_HOSTNAME` is set through the `config.properties` file at project root.

### 2.5.1 Usage

**Set profile in the execution invocation like this:** `mvn exec:java -Dexec.mainClass="roboy.dialog.DialogSystem" -Dprofile=NOROS`

**If running from within an IDE, edit the run configurations to include the profile as VM option:**

`-Dprofile=NOROS`

Without a specified profile, `DEFAULT` will be used. Please note that this profile requires setting a valid `ROS_HOSTNAME` address in the `config.properties` file to function properly! If ROS is not set up, use the `NOROS` profile to prevent the Dialog Manager from using ROS-dependent services.

## 2.5.2 Profiles

Profile	Description
DEFAULT	Used when no other profile is set, assumes that all requirements (ROS, Internet connection, speakers, mic) are fulfilled.
NOROS	To be used when ROS services are not set up, avoids calls to memory, speech synthesis, voice output, etc.
STAN-DALONE	To be used when running without Internet connection - this profile includes all restrictions of NOROS and also does not call DBpedia.
MEMORY-ONLY	To be used during Memory development, when no other ROS services are running. Only Neo4j-related ROS calls will be made.
DEBUG	With this setting, DM will run like DEFAULT but not shut down when ROS failures are encountered.

## 2.5.3 Extending

To extend or change the configurations, have a look at the instructions in the `roboy.dialog.Config` class.

## 2.6 Context

The goal of Context is to collect information about Roboy's environment and state. This information can be used by the DM classes and also to react upon situations that match certain conditions, such as turning the head of Roboy when the Interlocutor moves.

### 2.6.1 Architecture

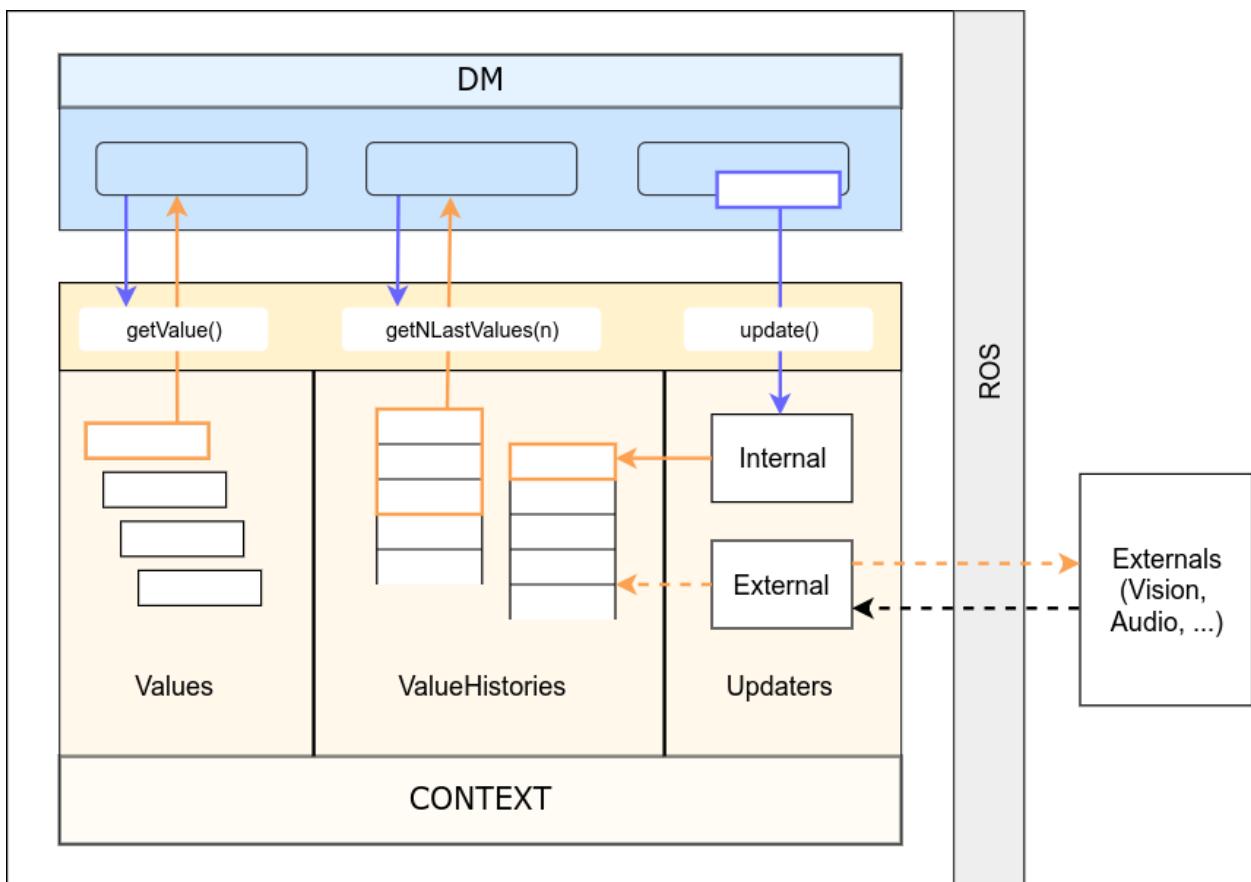
#### **alt** Context architecture

The Context supports storing data as a `Value` or `ValueHistory`. A `Value` only stores the latest data object that was pushed to it. A `ValueHistory` stores every value it receives and assigns each a unique key, thus the values can be ordered by their adding time.

### 2.6.2 How to add Values?

Here we describe how a new `Value` can be created and added to the Context. Sample implementations can be found inside `roboy.context.contextObjects` packge.

1. Consider what type of data will be stored in the `Value`. For this example, we chose `String`.
2. In the `contextObjects` directory, create a new class which inherits from the `Value` class. The final signature should look similar to: `public class SampleValue extends Value<String>` (replacing `String` with your type).
3. **Add the new `Value` in the main class `Context.java`:**
  - (a) In the standard constructor, initialize the `Value` object and add it to the builder of the value map:  
`put(SampleValue.class, sampleValue)`
  - (b) Make the value available over the enum `Values` within the `Context` class by adding a new element with your class name and stored data type. For example: `SAMPLE_VALUE(SampleValue.class, String.class);`



### 2.6.3 How to add ValueHistories?

ValueHistories extend the functionality of Values by storing all data objects sent to them. Over the `getNLastValues(int n)` method, a map with several most recent data objects can be retrieved, including their ordering.

Adding a ValueHistory is very much alike to adding a Value, just make sure to:

1. extend `ValueHistory<>` instead of `Value<>`,
2. in `Context.java`, add the new object to the Builder of `valueHistories` instead of `values`, and to the enum `ValueHistories` instead of `Values`.

### 2.6.4 How to add Updaters?

New values can only be added to the Context over an `Updater` instance. Internal updaters can be used by DM classes to actively add new values. External updaters run in separate threads and seek out new values, for example over a ROS connections to the Vision module.

#### Adding an External Updater

Currently, the only implementation of an external updater is the `IntervalUpdater` abstract class. Usage:

1. Create a class extending `IntervalUpdater` and implement its `update()` method. It should retrieve the values and finally add them over the `target.updateValue(value)` method call.
2. Add the updater to `externalUpdaters` in the `Context.java` constructor, setting its `target` parameter with the `Value` or `ValueHistory` object created in the same constructor.

#### Adding a new Internal Updater

1. Create a class extending `InternalUpdater<targetClass, valueType>`. The class and data type of the target `Value` or `ValueHistory` are the generic parameters for the updater.
2. A constructor is required for the class, simply match the `InternalUpdater` constructor and call `super(target)` within. An example is in the `DialogTopicsUpdater` class.
3. In the `Context` class constructor, initialize the updater and add it to the `internalUpdaters` map.
4. Add an entry to the `Updaters` enum, similarly as discussed above for `Values`.

## 2.7 Semantic Parser

Semantic parser is used to translate text representation into formal language representation. The aim is to be able to process user utterances and react upon them.

`roboy_parser` is based on *SEMPRE* <<http://nlp.stanford.edu/software/sempre/>>. It is currently being modified to fulfill Roboy Dialog system needs.

### 2.7.1 Installation

In order to use semantic parser, you need to:

- clone `roboy_parser` repository:

```
git clone http://github.com/Roboy/roboy_parser
```

- navigate to created repository:

```
cd roboy_parser
```

- build it:

```
ant freebase
```

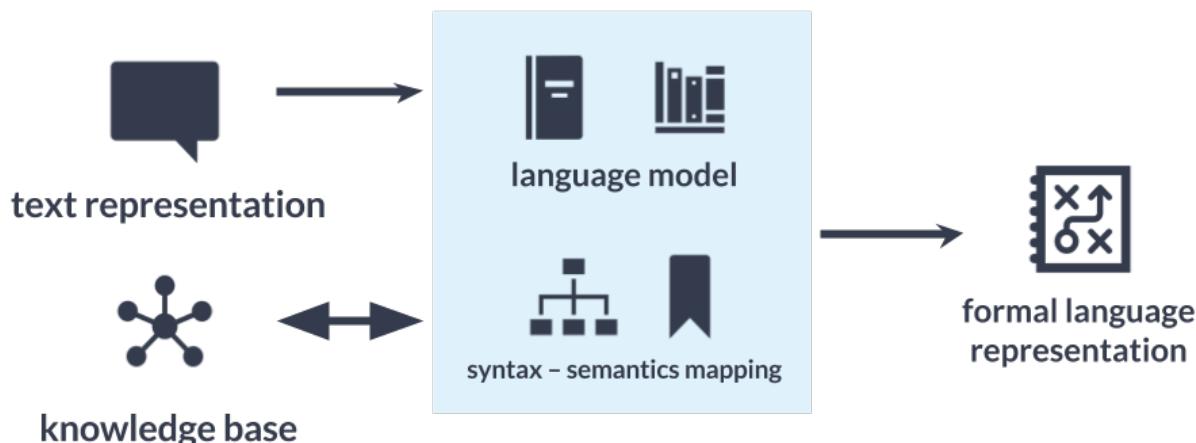
- run it:

```
./quick_start [options]
```

## 2.7.2 Architecture

Semantic parser is based on the language model and NLP algorithms that then apply rules to the utterance to translate it. Language model consists of: - set of grammar rules, - lexicon, - training dataset.

General architecture can be seen on the diagram below.



**alt** Semantic parser general architecture

## 2.7.3 Implementation

roboy\_parser is a separate Java project and is communicating using WebSocket. Dialog system has a client implemented in `SemanticParserAnalyzer.java` class. It is therefore part of Natural Language Understanding unit.

### Functionalities

Roboy parser currently has currently following functionalities:

Table 1: Semantic Parser algorithms used

Functionality	Software used	Summary
POS Tags	OpenNLP	Tagging tokens as part of speech
NER Tags	OpenNLP	Tool used to tag named entities like PERSON, NUMBER, ORGANIZATION
Triple extraction	OpenIE	Tool used to extract triples from sentences in form (Subject, Predicate, Object)

## 2.7.4 Usage

In order to run the parser, you need to run **roboy\_parser** first - see instructions on *project Github <http://github.com/Roboy/roboy\_parser* and then run Dialog System.

### Configurations

To test parser, you can run following configurations using `quick_start.sh` script. For more information refer to *project documentation <http://github.com/Roboy/roboy\_parser*

Table 2: Possible parser configurations

Command	Options
<code>./quick_start</code>	Default configuration. Using custom Roboy grammar and lexicons
<code>./quick_start freebase</code>	Example setup to test Freebase functionality

## 2.8 API

### class

Abstract super class for states that fork between two possible subsequent states.

The `determineSuccess` method needs to be implemented by subclass to determine if the success or failure state should be moved into next.

Subclassed by `roboy.dialog.personality.states.ConverseState`, `roboy.dialog.personality.states.GenerativeCommunicationState`,  
`roboy.dialog.personality.states.IdleState`,  
`roboy.dialog.personality.states.GreetingState`,  
`roboy.dialog.personality.states.InquiryState`,  
`roboy.dialog.personality.states.IntroductionState`,  
`roboy.dialog.personality.states.LocationDBpedia`,  
`roboy.dialog.personality.states.PersonalFollowUpState`,  
`roboy.dialog.personality.states.PersonalQAState`

### Public Functions

```
State roboy.dialog.personality.states.AbstractBooleanState.getSuccess()
void roboy.dialog.personality.states.AbstractBooleanState.setSuccess(State success)
Sets the state Roboy moves into if the determineSuccess method returns true.
```

### Parameters

- `success`: The following state

```
State roboy.dialog.personality.states.AbstractBooleanState.getFailure()
```

---

```
void roboy.dialog.personality.states.AbstractBooleanState.setFailure(State failure)
Sets the state Roboy moves into if the determineSuccess method returns false.
```

#### Parameters

- failure: The following state

```
void roboy.dialog.personality.states.AbstractBooleanState.setNextState(State state)
void roboy.dialog.personality.states.AbstractBooleanState.setSuccessTexts(List< String> texts)
void roboy.dialog.personality.states.AbstractBooleanState.setFailureTexts(List< String> texts)
Reaction roboy.dialog.personality.states.AbstractBooleanState.react(Interpretation input)
```

### Protected Functions

```
abstract boolean roboy.dialog.personality.states.AbstractBooleanState.determineSuccess()
Needs to be implemented by subclasses.
```

If the method returns true the state machine moves to the success state, if it returns false it moves to the failure state.

**Return** true or false depending on the examined condition of the method

#### Parameters

- input: The interpretation of all inputs

### Protected Attributes

```
State roboy.dialog.personality.states.AbstractBooleanState.success
State roboy.dialog.personality.states.AbstractBooleanState.failure
```

### Private Members

```
List<String> roboy.dialog.personality.states.AbstractBooleanState.successTexts = Lists.newArrayList()
List<String> roboy.dialog.personality.states.AbstractBooleanState.failureTexts = Lists.newArrayList()
```

```
template <V>
interface roboy:contextAbstractValue< V >
```

Stores a single value.

On update, the value is overwritten.

Subclassed by *roboy.context.AbstractValueHistory< K, V >*, *roboy.context.Value< V >*

### Public Functions

```
V roboy.context.AbstractValue< V >.getValue()
void roboy.context.AbstractValue< V >.updateValue(V key)
template <K, V>
```

**interface** *roboy::contextAbstractValueHistory*

*ValueHistory* maintains a map containing all (current and past) values.

These values are accessible over the getLastNValues method.

### Public Functions

`Map<K, V> roboy.context.AbstractValueHistory< K, V >.getLastNValues(int n)`

**interface** *roboy::dialog::actionAction*

The marker interface for an action.

The interface is empty, since different output devices will require different informations in an action. The most important action is the *SpeechAction* which is used for communication.

Subclassed by *roboy.dialog.action.FaceAction*, *roboy.dialog.action.ShutDownAction*,  
*roboy.dialog.action.SpeechAction*

**interface** *roboy::linguistics::sentenceanalysisAnalyzer*

All linguistic analyses implement the *Analyzer* interface.

An analyzer always takes an existing interpretation of a sentence and returns one including its own analysis results (usually an enriched version of the input interpretation).

Subclassed by *roboy.linguistics.sentenceanalysis.AnswerAnalyzer*, *roboy.linguistics.sentenceanalysis.DictionaryBasedSentenceType*,  
*roboy.linguistics.sentenceanalysis.EmotionAnalyzer*, *roboy.linguistics.sentenceanalysis.IntentAnalyzer*,  
*roboy.linguistics.sentenceanalysis.OntologyNERAnalyzer*, *roboy.linguistics.sentenceanalysis.OpenNLPParser*,  
*roboy.linguistics.sentenceanalysis.OpenNLPPPOSTagger*, *roboy.linguistics.sentenceanalysis.Preprocessor*,  
*roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer*, *roboy.linguistics.sentenceanalysis.SentenceAnalyzer*,  
*roboy.linguistics.sentenceanalysis.SimpleTokenizer*

### Public Functions

`Interpretation roboy.linguistics.sentenceanalysis.Analyzer.analyze(Interpretation sentence)`

**class**

Utters the given text and moves to the given state.

Used for telling anecdotes.

### Public Functions

`roboy.dialog.personality.states.AnecdoteState.AnecdoteState(State nextState, String anecdote)`

`List<Interpretation> roboy.dialog.personality.states.AnecdoteState.act()`

`Reaction roboy.dialog.personality.states.AnecdoteState.react(Interpretation input)`

### Private Members

`State roboy.dialog.personality.states.AnecdoteState.nextState`

`String roboy.dialog.personality.states.AnecdoteState.anecdote`

**class**

Checks the predicate argument structures produced by the *OpenNLPParser* analyzer and looks for possible answers to questions in them.

It creates the outputs *Linguistics.OBJ\_ANSWER* for situations where the answer to the question is in the object of the sentence (e.g. “Frank” in the sentence “I am Frank” to the question “Who are you?”) and *Linguistics.PRED\_ANSWER* if it is in the predicate or in the predicate and the object combined (e.g. “swimming” in the answer “I like swimming” to the question “What is your hobby?”).

**Public Functions**

```
Interpretation roboy.linguistics.sentenceanalysis.AnswerAnalyzer.analyze(Interpretation)
class roboy::linguistics::sentenceanalysisAnswerAnalyzerTest
```

**Public Functions**

```
void roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.testName()
void roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.testOccupation()
void roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.testOrigin()
void roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.testHobby()
void roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.testMovie()
```

**Private Functions**

```
String roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.analyze(String sentence)
String roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.analyzePred(String sentence)
```

**Private Static Attributes**

```
final SimpleTokenizer roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.tokenizer =
final OpenNLPPPOSTagger roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.pos = new OpenNLPPPOSTagger()
final OpenNLPParser roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.parser = new OpenNLPParser()
final AnswerAnalyzer roboy.linguistics.sentenceanalysis.AnswerAnalyzerTest.answer = new AnswerAnalyzer()

template <H, V>
class roboy::contextAttributeManager
```

The collection of values, split into valueHistories (H) and single values (V).

**Protected Attributes**

```
ImmutableClassToInstanceMap<AbstractValueHistory> roboy.context.AttributeManager< H extends E>
ImmutableClassToInstanceMap<AbstractValue> roboy.context.AttributeManager< H extends E>
```

### Package Functions

```
protected<T> T roboy.context.AttributeManager< H extends ExternalContextInterface, V e
protected<K, T> Map<K, T> roboy.context.AttributeManager< H extends ExternalContextInte
protected<T> T roboy.context.AttributeManager< H extends ExternalContextInterface, V e
class
Using Bing to perform speech to text.
Requires internet connection.
```

### Public Functions

```
roboy.io.BingInput.BingInput(RosMainNode node)
Input roboy.io.BingInput.listen()
```

### Private Members

```
RosMainNode roboy.io.BingInput.rosMainNode
class
Uses Bing for text to speech.
Requires internet connection.
```

### Public Functions

```
void roboy.io.BingOutput.act(List< Action > actions)
void roboy.io.BingOutput.say(String text)
class
Should perform the celebrity look-a-like vision input.
Isn't implemented yet.
```

### Public Functions

```
Input roboy.io.CelebritySimilarityInput.listen()
class
Checks whether it was asked 'Whom do I look like' or something similar and answers with the most similar
celebrity if it was detected by vision.
If no trigger sentence was used, the given inner state is executed instead.
```

### Public Functions

```
roboy.dialog.personality.states.CelebrityState.CelebrityState(State inner)
void roboy.dialog.personality.states.CelebrityState.setTop(State top)
List<Interpretation> roboy.dialog.personality.states.CelebrityState.act()
```

---

```
Reaction roboy.dialog.personality.states.CelebrityState.react(Interpretation input)
```

### Private Members

```
State roboy.dialog.personality.states.CelebrityState.inner
State roboy.dialog.personality.states.CelebrityState.top
```

### Private Static Attributes

Lists.stringList( "whom do i look like", "who do i look like", "which star do i look like", "which celebrity do i look like", "how do i look", "whom do i resemble", "who do i resemble", "which star do i resemble", "which celebrity do i resemble", "whom do i remind you of", "who do i remind you of", "who am i" ) ]

Lists.stringList( "You look one hundred percent like ", "You totally look like ", "You bear a very striking resemblance to ", "You must be the identical twin of ", "You look a lot like ", "You seem to be the doubleganger of ", "The look, the attitude. Yeah, you are totally a ", "You look like ", "That is easy. You are a ", "You resemble ", "You could easily pass for ", "You are the very picture of ", "You remind me a lot of ", "You take after ", "You were clearly created in the image of ", "You are like a poor version of ", "What is up with your face? You look like if Picasso tried to draw ", "Looks like they finally managed to clone ", "You are like an impersonator of ", "I am unable to distinguish between you and ", "You have quite some of the features of ", "Is that you? " ) ]

```
class
```

Cerevoice text to speech.

### Public Functions

```
roboy.io.CerevoiceOutput.CerevoiceOutput(RosMainNode node)
void roboy.io.CerevoiceOutput.act(List< Action > actions)
void roboy.io.CerevoiceOutput.say(String text)
```

### Private Members

```
RosMainNode roboy.io.CerevoiceOutput.rosMainNode
```

```
class
```

### Public Functions

```
void roboy.io.CommandLineCommunication.setPersonality(Personality p)
void roboy.io.CommandLineCommunication.communicate()
```

### Private Functions

```
void roboy.io.CommandLineCommunication.talk(List< Action > actions)
```

### Private Members

```
Personality roboy.io.CommandLineCommunication.personality
SentenceAnalyzer roboy.io.CommandLineCommunication.analyzer
```

### class

Uses the command line as input device.

### Public Functions

```
Input roboy.io.CommandLineInput.listen()
```

### Protected Functions

```
void roboy.io.CommandLineInput.finalize()
```

### Private Members

```
Scanner roboy.io.CommandLineInput.sc = new Scanner(System.in)
```

### class

Uses the command line as output device.

### Public Functions

```
void roboy.io.CommandLineOutput.act(List< Action > actions)
```

### interface roboy::ioCommunication

Subclassed by *roboy.io.CommandLineCommunication*

### Public Functions

```
void roboy.io.Communication.setPersonality(Personality p)
```

```
void roboy.io.Communication.communicate()
```

### class roboy::utilConcept

Protege memory concept.

### Public Functions

```
roboy.util.Concept.Concept()
```

```
roboy.util.Concept.Concept(Map< String, Object > attrs)
```

```
roboy.util.Concept.Concept(String name)
```

```
void roboy.util.Concept.addAttribute(String property, Object value)
```

```
void roboy.util.Concept.addAttributes(Map< String, Object > attrs)
```

```
Map<String, Object> roboy.util.Concept.getAttributes()
```

---

```

Object roboy.util.Concept.getAttribute(String key)
String roboy.util.Concept.getProperties()
String roboy.util.Concept.getValues()
boolean roboy.util.Concept.hasAttribute(String property)
Object roboy.util.Concept.retrieve()
boolean roboy.util.Concept.updateInMemory()
int roboy.util.Concept.getID()

```

## Private Members

```

Map<String, Object> roboy.util.Concept.attributes
class roboy::linguisticsConcept

```

## Package Attributes

```

String roboy.linguistics.Concept.id
class roboy::dialogConfig
Save runtime configurations (profiles) for Roboy.

1) Configuration variables define alternating behaviors. 2) To create a combination of configurations, add a new profile to Configurations and implement its setProfile method.

```

## Public Functions

```

roboy.dialog.Config.Config(ConfigurationProfile profile)
Constructor switching to the correct profile.

```

## Public Static Functions

```

static ConfigurationProfile roboy.dialog.Config.getProfileFromEnvironment(Retrieving profileString)
ConfigurationProfile instance which matches the profileString.

```

### Parameters

- profileString: String value of the configuration profile name.

## Public Static Attributes

```

boolean roboy.dialog.Config.STANDALONE = false
If true, Roboy avoids using network-based services such as DBpedia as well as ROS.

boolean roboy.dialog.Config.NOROS = false
If true, Roboy avoids using ROS-based services.

boolean roboy.dialog.Config.SHUTDOWN_ON_ROS_FAILURE = true
If true, Roboy will not continue executing if the ROS main node fails to initialize.

```

```
boolean roboy.dialog.Config.SHUTDOWN_ON_SERVICE_FAILURE = true
    If true, Roboy will not continue executing if any of the ROS services failed to initialize.

String roboy.dialog.Config.ROS_HOSTNAME = null
    ROS hostname, will be fetched from the configuration file in the DEFAULT profile.

boolean roboy.dialog.Config.MEMORY = true
    If true, memory will be queried.

    Ensure that if NOROS=false, then MEMORY=true. When NOROS=true, MEMORY can be either true or
    false.

int roboy.dialog.Config.PARSER_PORT = -1
    Semantic parser socket port.

boolean roboy.dialog.Config.DEMO_GUI = false
    Context GUI demo trigger.

    Set manually, if wanted.
```

### Private Functions

```
void roboy.dialog.Config.setDefaultProfile()
void roboy.dialog.Config.setNoROSProfile()
void roboy.dialog.Config.setStandaloneProfile()
void roboy.dialog.Config.setDebugProfile()
void roboy.dialog.Config.setMemoryProfile()
void roboy.dialog.Config.initializeYAMLConfig()
```

### Private Members

```
YAMLConfiguration roboy.dialog.Config.yamlConfig
```

### Private Static Attributes

```
String roboy.dialog.Config.yamlConfigFile = "config.properties"
    Configuration file to store changing values.

enum roboy::dialog::ConfigConfigurationProfile
    List of profile names.

    The variables are set in the corresponding set<name>Profile() method. String values make it possible to define
    the profile in start command with: -Dprofile=<profileString>
```

### Public Functions

```
roboy.dialog.Config.ConfigurationProfile.ConfigurationProfile(String profile)
```

## Public Members

```
roboy.dialog.Config.ConfigurationProfile.DEFAULT = ("DEFAULT")
roboy.dialog.Config.ConfigurationProfile.NOROS = ("NOROS")
roboy.dialog.Config.ConfigurationProfile.STANDALONE = ("STANDALONE")
roboy.dialog.Config.ConfigurationProfile.DEBUG = ("DEBUG")
roboy.dialog.Config.ConfigurationProfile.MEMORY = ("MEMORY")
String roboy.dialog.Config.ConfigurationProfile.profileName
```

### class

Singleton class serving as an interface to access all context objects.

Takes care of correct initialization of attribute histories and updaters.

Queries to values are handled through the inherited *AttributeManager* methods.

For usage examples, check out ContextTest.java

## Public Members

```
final HashMap<Class, InternalUpdater> roboy.context.Context.internalUpdaters = new HashMap<
```

## Public Static Functions

```
static Context roboy.context.Context.getInstance()
```

## Package Functions

```
public<V> void roboy.context.Context.updateValue(Updaters updater, V value)
    Directly update an attribute.
```

### Parameters

- **updater:** The name of the *Value* or *ValueHistory* object.
- **value:** Data to put into the *Value* or *ValueHistory* object.

## Private Functions

```
roboy.context.Context.Context()
```

## Private Members

```
final ArrayList<ExternalUpdater> roboy.context.Context.externalUpdaters = new ArrayList<>()
```

### Private Static Attributes

```
Context roboy.context.Context.context  
class roboy::context::GUIContextGUI
```

A simple GUI with the goal of showing the attribute values and histories in the *Context*.

### Public Static Functions

```
static void roboy.context.GUI.ContextGUI.run()
```

### Private Functions

```
roboy.context.GUI.ContextGUI.ContextGUI()  
void roboy.context.GUI.ContextGUI.prepareGUI()  
void roboy.context.GUI.ContextGUI.startFrame()  
void roboy.context.GUI.ContextGUI.updateValues()  
void roboy.context.GUI.ContextGUI.updateHistories()
```

### Private Members

```
JFrame roboy.context.GUI.ContextGUI.mainFrame  
TitledBorder roboy.context.GUI.ContextGUI.valueBorder  
 JPanel roboy.context.GUI.ContextGUI.valuePanel  
 Map<Context.Values, JLabel> roboy.context.GUI.ContextGUI.valueDisplays  
 Map<Context.ValueHistories, JScrollPane> roboy.context.GUI.ContextGUI.historyDisplays  
 TitledBorder roboy.context.GUI.ContextGUI.historyBorder  
 JPanel roboy.context.GUI.ContextGUI.historyPanel  
 JPanel roboy.context.GUI.ContextGUI.controlPanel
```

### Private Static Attributes

```
int roboy.context.GUI.ContextGUI.MAX_HISTORY_VALUES = 10  
int roboy.context.GUI.ContextGUI.FULL_WIDTH = 400  
int roboy.context.GUI.ContextGUI.FULL_HEIGHT = 300  
int roboy.context.GUI.ContextGUI.ATTR_WIDTH = 390  
int roboy.context.GUI.ContextGUI.ATTR_HEIGHT = 50  
int roboy.context.GUI.ContextGUI.HISTORY_HEIGHT = 100  
String roboy.context.GUI.ContextGUI.NO_VALUE = "<not initialized>"  
class roboy::context::visionContextContextTest
```

## Public Functions

```
void roboy.context.visionContext.ContextTest.getLastAttributeValue()
```

Checks that the values of FACE\_COORDINATES get automatically updated.

```
void roboy.context.visionContext.ContextTest.setAndGetDialogTopics()
```

```
enum roboy::dialog::personality::DefaultPersonalityCONVERSATIONAL_STATE
```

## Public Members

```
roboy.dialog.personality.DefaultPersonality.CONVERSATIONAL_STATE.GREETING
```

```
roboy.dialog.personality.DefaultPersonality.CONVERSATIONAL_STATE.INTRODUCTION
```

```
roboy.dialog.personality.DefaultPersonality.CONVERSATIONAL_STATE.SMALL_TALK
```

```
roboy.dialog.personality.DefaultPersonality.CONVERSATIONAL_STATE.FAREWELL
```

```
class
```

## Public Functions

```
roboy.dialog.personality.states.ConverseState.ConverseState()
```

```
List<Interpretation> roboy.dialog.personality.states.ConverseState.act()
```

```
Reaction roboy.dialog.personality.states.ConverseState.react(Interpretation input)
```

## Protected Functions

```
boolean roboy.dialog.personality.states.ConverseState.determineSuccess(Interpretation
```

## Private Members

```
State roboy.dialog.personality.states.ConverseState.inner
```

```
class roboy::context::contextObjectsCoordinateSet
```

A coordinate set data structure for the interlocutor face.

## Public Functions

```
roboy.context.contextObjects.CoordinateSet.CoordinateSet(double x, double y, double z)
```

## Package Attributes

```
final double roboy.context.contextObjects.CoordinateSet.x
```

```
final double roboy.context.contextObjects.CoordinateSet.y
```

```
final double roboy.context.contextObjects.CoordinateSet.z
```

```
class
```

## Public Functions

```
roboy.dialog.personality.CuriousPersonality.CuriousPersonality()
```

```
List<Action> roboy.dialog.personality.CuriousPersonality.answer(Interpretation input)
```

The central method of a personality.

Given an interpretation of all inputs (audio, visual, ...) to Roboy, this method decides which actions to perform in response.

**Return** A list of actions to perform in response

### Parameters

- `input`: The interpretation of the inputs

## Public Static Functions

```
static void roboy.dialog.personality.CuriousPersonality.main(String[] args)
```

## Private Functions

```
Triple roboy.dialog.personality.CuriousPersonality.remember(String predicate, String a
```

## Private Members

```
List<Triple> roboy.dialog.personality.CuriousPersonality.memory
```

### class

Restores information from the DBpedia.

## Public Functions

```
boolean roboy.memory.DBpediaMemory.save(Relation object)
```

```
List<Relation> roboy.memory.DBpediaMemory.retrieve(Relation object)
```

Retrive all matching relations from DBpedia.

## Public Static Functions

```
static DBpediaMemory roboy.memory.DBpediaMemory.getInstance()
```

Loading DBpedia takes resources, so only do it once.

### Return

```
static LinkedHashSet<String> roboy.memory.DBpediaMemory.buildQueries(Relation object)
```

## Private Functions

```
roboy.memory.DBpediaMemory.DBpediaMemory()
```

**Private Members**

```
Map<String, String> roboy.memory.DBpediaMemory.forms
```

**Private Static Attributes**

```
DBpediaMemory roboy.memory.DBpediaMemory.dbpediaMemory
final Map<String, String> roboy.memory.DBpediaMemory.supportedRelations
class
```

**Public Functions**

```
List<Action> roboy.dialog.personality.DefaultPersonality.answer(Interpretation input)
```

The central method of a personality.

Given an interpretation of all inputs (audio, visual, ...) to Roboy, this method decides which actions to perform in response.

**Return** A list of actions to perform in response

**Parameters**

- **input:** The interpretation of the inputs

**Private Functions**

```
String roboy.dialog.personality.DefaultPersonality.stripFromFront(String input, List< String > list)
String roboy.dialog.personality.DefaultPersonality.random(List< String > list)
boolean roboy.dialog.personality.DefaultPersonality.checkForTerm(String input, List< String > list)
```

**Private Members**

```
CONVERSATIONAL_STATE roboy.dialog.personality.DefaultPersonality.state = CONVERSATIONAL_STATE.GREETING
```

**Private Static Attributes**

```
Arrays.asList("hello", "hi", "greetings", "good morning", "howdy", "good day", "hey") ]
```

```
Arrays.asList("ciao", "goodbye", "cheerio", "bye", "see you", "farewell", "bye-bye") ]
```

```
Arrays.asList("enthusiastic", "awesome", "great", "very good", "dope", "smashing", "happy", "cheerful", "good", "phantastic") ]
```

```
Arrays.asList("yes", "yeah", "indeed", "i am") ]
```

```
Arrays.asList("no", "never", "not sure") ]
```

```
Arrays.asList("i am", "i'm", "my name is", "call me") ]
```

```
class roboy::linguisticsDetectedEntity
```

## Public Functions

```
roboy.linguistics.DetectedEntity.DetectedEntity(Entity entity, int tokenIndex)
Entity roboy.linguistics.DetectedEntity.getEntity()
int roboy.linguistics.DetectedEntity.getTokenIndex()
```

## Private Members

```
Entity roboy.linguistics.DetectedEntity.entity
int roboy.linguistics.DetectedEntity.tokenIndex
```

### class roboy::newDialog::DialogStateMachine

State machine to manage dialog states.

Dialog state machines can be written to files and loaded from them later.

Personalities can be implemented using a dialog state machine.

Subclassed by *roboy.newDialog.StateBasedPersonality*

## Public Functions

```
roboy.newDialog.DialogStateMachine.DialogStateMachine()
roboy.newDialog.DialogStateMachine.DialogStateMachine(boolean enableDebug)
State roboy.newDialog.DialogStateMachine.getInitialState()
void roboy.newDialog.DialogStateMachine.setInitialState(State initial)
```

Set the initial state of this state machine.

The state will be automatically added to the machine. If active state was null, it will be set to the new initial state.

### Parameters

- initial: initial state

```
void roboy.newDialog.DialogStateMachine.setInitialState(String identifier)
State roboy.newDialog.DialogStateMachine.getActiveState()
void roboy.newDialog.DialogStateMachine.setActiveState(State s)
void roboy.newDialog.DialogStateMachine.setActiveState(String identifier)
State roboy.newDialog.DialogStateMachine.getStateByIdentifier(String identifier)
void roboy.newDialog.DialogStateMachine.addState(State s)
void roboy.newDialog.DialogStateMachine.loadFromString(String s)
void roboy.newDialog.DialogStateMachine.loadFromFile(File f)
void roboy.newDialog.DialogStateMachine.saveToFile(File f)
String roboy.newDialog.DialogStateMachine.toJsonString()
String roboy.newDialog.DialogStateMachine.toString()
boolean roboy.newDialog.DialogStateMachine.equals(Object obj)
```

## Private Functions

```
void roboy.newDialog.DialogStateMachine.loadFromJSON(JsonElement json)
JsonObject roboy.newDialog.DialogStateMachine.toJsonObject()
```

## Private Members

```
HashMap<String, State> roboy.newDialog.DialogStateMachine.identifierToState
State roboy.newDialog.DialogStateMachine.activeState
State roboy.newDialog.DialogStateMachine.initState
boolean roboy.newDialog.DialogStateMachine.enableDebug
class roboy::newDialogDialogStateMachineTest
```

## Public Functions

```
void roboy.newDialog.DialogStateMachineTest.machineEqualsItself()
void roboy.newDialog.DialogStateMachineTest.stringEqualsCode()
void roboy.newDialog.DialogStateMachineTest.notEqualsNoInitialState()
void roboy.newDialog.DialogStateMachineTest.notEqualsDifferentStates()
void roboy.newDialog.DialogStateMachineTest.notEqualsDifferentTransitions()
void roboy.newDialog.DialogStateMachineTest.activeStateIsSetToInitialState()
void roboy.newDialog.DialogStateMachineTest.machineContainsAllStates()
void roboy.newDialog.DialogStateMachineTest.transitionsAreOK()
void roboy.newDialog.DialogStateMachineTest.fallbackIsOK()
```

## Private Static Functions

```
static DialogStateMachine roboy.newDialog.DialogStateMachineTest.fromCode()
```

## Private Static Attributes

```
    "initialState": "Greetings",\n" + "states": [\n" + "\n" + " " "identifier": "Farewell",\n"
+ " " "implementation": "roboy.newDialog.states.toyStates.ToyFarewellState",\n" + " " "transi-
tions": {} \n" + " },\n" + "\n" + " " "identifier": "Greetings",\n" + " " "implementation":
"roboy.newDialog.states.toyStates.ToyGreetingsState",\n" + " " "fallback": "Farewell",\n" + " "
"transitions": {} \n" + " " "next": "Farewell",\n" + " " "noHello": "Farewell"\n" + " }\n" + " }\n" +
"]\n"]
```

```
class roboy::dialogDialogSystem
```

The dialog manager's main class.

Here, the used components are put together and executed using the main method. In the future, the different combinations of components should probably be transferred to configuration files.

The workflow in the dialog manager is the following:

1. Input devices produce an Input object
2. The Input object is transformed into an Interpretation object containing the input sentence in the Linguistics.SENTENCE attribute and all other lists of the Input object in the corresponding fields
3. Linguistic Analyzers are used on the Interpretation object to add additional information
4. The Personality class takes the Interpretation object and decides how to answer to this input
5. The list of actions returned by *Personality.answer* is performed by the Output devices
6. If one of these actions is a ShutDownAction the program terminates
7. Otherwise repeat

Input devices:

- For testing from command line: CommandLineInput
- For speech to text: BingInput (requires internet)
- For combining multiple inputs: MultiInputDevice
- Others for specific tasks

Analyzers:

- Tokenization: SimpleTokenizer
- Part-of-speech-tagging: OpenNLPPPOSTagger
- Semantic role labeling: OpenNLPParser
- DBpedia question answering: AnswerAnalyzer
- Other more stupid ones

Personalities:

- SmallTalkPersonality: main one
- Others for testing specific things

Output devices:

- For testing with command line: CommandLineOutput
- For text to speech: BingOutput (requires internet)
- For combining multiple outputs: MultiOutputDevice
- For text to speech + facial expressions: CerevoiceOutput
- For facial expressions: EmotionOutput
- For text to speech (worse quality): FreeTTSSOutput

The easiest way to create ones own Roboy communication application is to pick the input and output devices provided here, use the tokenization, POS tagging and possibly semantic role labeling (though still under development) if needed and write an own personality. If one wants to use the DBpedia, Protege, generative model or state machine stuff, one has to dig deeper into the small talk personality and see how it is used there.

### Public Static Functions

```
static void roboy.dialog.DialogSystem.main(String[] args)  
class roboy::context::contextObjectsDialogTopics : public roboy::context::ValueHistory<String>
```

---

```
class roboy::context::contextObjectsDialogTopicsUpdater : public roboy::context::InternalUpdater<DialogTopics, String>
```

Updater available to all DM for adding new values to the *DialogTopics* attribute.

### Public Functions

```
roboy.context.contextObjects.DialogTopicsUpdater.DialogTopicsUpdater(DialogTopics targ
```

**class**

Checks the sentence type by stupidly looking at the first word of the sentence and hoping that there is a known question word.

Puts the answer in the sentenceType variable of the *Interpretation* object.

### Public Functions

```
Interpretation roboy.linguistics.sentenceanalysis.DictionaryBasedSentenceTypeDetector.
```

### Private Functions

```
SENTENCE_TYPE roboy.linguistics.sentenceanalysis.DictionaryBasedSentenceTypeDetector.d
```

```
class roboy::linguistics::sentenceanalysisDictionaryBasedSentenceTypeDetectorTest
```

### Public Functions

```
void roboy.linguistics.sentenceanalysis.DictionaryBasedSentenceTypeDetectorTest.testWh
```

### Private Members

```
DictionaryBasedSentenceTypeDetector roboy.linguistics.sentenceanalysis.DictionaryBased
```

```
SimpleTokenizer roboy.linguistics.sentenceanalysis.DictionaryBasedSentenceTypeDetector
```

```
class
```

A phonetic encoder using the method double metaphone that maps words to their phonetic base form so that words that are written differently but sound similar receive the same form.

This is intended to be used to correct terms that Roboy misunderstood, but currently is not in use.

### Public Functions

```
roboy.linguistics.phonetics.DoubleMetaphoneEncoder.DoubleMetaphoneEncoder(DoubleMetapho
```

```
String roboy.linguistics.phonetics.DoubleMetaphoneEncoder.encode(String input)
```

### Package Attributes

```
DoubleMetaphone roboy.linguistics.phonetics.DoubleMetaphoneEncoder.doubleMetaphone
```

**class**

Checks for a handful of keywords and stores more or less fitting emotions in the *Linguistics.EMOTION* feature that is later read out and fed to the facial expression output module.

**Public Functions**

```
Interpretation roboy.linguistics.sentenceanalysis.EmotionAnalyzer.analyze(Interpretation)
```

**class**

Roboy's facial expression output.

**Public Functions**

```
roboy.io.EmotionOutput.EmotionOutput(RosMainNode node)  
void roboy.io.EmotionOutput.act(List< Action > actions)  
void roboy.io.EmotionOutput.act(Action action)
```

**Private Members**

```
RosMainNode roboy.io.EmotionOutput.rosMainNode
```

**class roboy::linguisticsEntity**

**Public Functions**

```
roboy.linguistics.Entity.Entity(String term)  
String roboy.linguistics.Entity.getForm(String form)  
Map<String, String> roboy.linguistics.Entity.getForms()
```

**Private Members**

```
Map<String, String> roboy.linguistics.Entity.forms
```

**interface roboy::contextExternalContextInterface**

Interface for an enum which lists *Context* values and valueHistories.

Methods enable retrieving values over generic methods with *AttributeManager*.

Subclassed by *roboy.context.Context.ValueHistories*, *roboy.context.Context.Values*

**Public Functions**

```
Class roboy.context.ExternalContextInterface.getClassType()  
Class roboy.context.ExternalContextInterface.getReturnType()
```

**class** *roboy::contextExternalUpdater*

For Values which should be updated upon incoming data or at regular intervals, this class fetches and passes the values.

Subclassed by *roboy.context.IntervalUpdater< T >*

**Protected Functions**

```
abstract void roboy.context.ExternalUpdater.update()
```

**class**

*Action* used if the dialogue manager wants Roboy to express a certain facial expression, like being angry, neutral or moving its lips (speak).

**Public Functions**

```
roboy.dialog.action.FaceAction.FaceAction(String state)
```

Constructor.

Duration is set to 1.

**Parameters**

- state: The facial expression. Possible values: angry, neutral, speak

```
roboy.dialog.action.FaceAction.FaceAction(String state, int duration)
```

Constructor.

**Parameters**

- state: The facial expression. Possible values: angry, neutral, speak
- duration: How long Roboy should display the given facial expression

```
String roboy.dialog.action.FaceAction.getState()
```

```
int roboy.dialog.action.FaceAction.getDuration()
```

**Private Members**

```
String roboy.dialog.action.FaceAction.state
```

```
int roboy.dialog.action.FaceAction.duration
```

**class** *roboy::context::contextObjectsFaceCoordinates* : public *roboy::context::Value<CoordinateSet>*

xzy-coordinates of a person in the field of vision.

**class** *roboy::context::contextObjectsFaceCoordinatesUpdater* : public *roboy::context::IntervalUpdater<FaceCoordinates>*

Asynchronously triggers ROS queries for face coordinates (in the future).

**Public Functions**

```
roboy.context.contextObjects.FaceCoordinatesUpdater.FaceCoordinatesUpdater(FaceCoordinatesUpdater)
```

### Protected Functions

```
void roboy.context.contextObjects.FaceCoordinatesUpdater.update()  
class  
Says goodbye.
```

### Public Functions

```
roboy.dialog.personality.states.FarewellState.FarewellState()  
List<Interpretation> roboy.dialog.personality.states.FarewellState.act()  
Reaction roboy.dialog.personality.states.FarewellState.react(Interpretation input)  
class  
Free TTS text to speech.
```

### Public Functions

```
roboy.io.FreeTTSOutput.FreeTTSOutput()  
void roboy.io.FreeTTSOutput.act(List< Action > actions)
```

### Public Static Functions

```
static void roboy.io.FreeTTSOutput.main(String[] args)
```

### Private Members

```
Voice roboy.io.FreeTTSOutput.voice  
class
```

### Public Functions

```
List<Interpretation> roboy.dialog.personality.states.GenerativeCommunicationState.act()
```

### Protected Functions

```
boolean roboy.dialog.personality.states.GenerativeCommunicationState.determineSuccess()
```

### Private Members

```
boolean roboy.dialog.personality.states.GenerativeCommunicationState.first = true  
class  
Says hello.
```

**Public Functions**

```
List<Interpretation> roboy.dialog.personality.states.GreetingState.act()
Reaction roboy.dialog.personality.states.GreetingState.react(Interpretation input)
```

**Protected Functions**

```
boolean roboy.dialog.personality.states.GreetingState.determineSuccess(Interpretation input)
class
```

**Public Functions**

```
List<Interpretation> roboy.dialog.personality.states.IdleState.act()
```

**Protected Functions**

```
boolean roboy.dialog.personality.states.IdleState.determineSuccess(Interpretation input)
class roboy::ioInput
```

The result of an input device consists of a sentence, if it is an audio device, and an arbitrary map of lists.

**Public Functions**

```
roboy.io.Input.Input(String sentence)
roboy.io.Input.Input(String sentence, Map< String, Object > attributes)
```

**Public Members**

```
String roboy.io.Input.sentence
Map<String, Object> roboy.io.Input.attributes
```

```
interface roboy::ioInputDevice
```

An input device must listen and return an *Input* object.

Subclassed by *roboy.io.BingInput*, *roboy.io.CelebritySimilarityInput*, *roboy.io.CommandLineInput*, *roboy.io.MultiInputDevice*, *roboy.io.RoboyNameDetectionInput*, *roboy.io.UdpInput*

**Public Functions**

```
Input roboy.io.InputDevice.listen()
```

```
class
```

Asks a given question, checks the answer for a list of given terms.

Moves to the success state if the answer consists one of these terms and to the failure state if not.

## Public Functions

```
roboy.dialog.personality.states.InquiryState.InquiryState(String inquiry, List< String > successTerms, String failureText)
```

### Parameters

- inquiry: The question asked
- successTerms: The list of terms that is checked for
- failureText: Currently, not used

```
List<Interpretation> roboy.dialog.personality.states.InquiryState.act()
```

## Protected Functions

```
boolean roboy.dialog.personality.states.InquiryState.determineSuccess(Interpretation interpretation)
```

## Private Members

```
String roboy.dialog.personality.states.InquiryState.inquiry
List<String> roboy.dialog.personality.states.InquiryState.successTerms
String roboy.dialog.personality.states.InquiryState.failureText
```

### class

Calls a machine learning model to determine if the utterance of the other person represents one of the learned intents.

Stores the highest scoring intent in the *Linguistics.INTENT* feature and the score in the *Linguistics.INTENT\_DISTANCE* feature.

## Public Functions

```
roboy.linguistics.sentenceanalysis.IntentAnalyzer.IntentAnalyzer(RosMainNode ros)
Interpretation roboy.linguistics.sentenceanalysis.IntentAnalyzer.analyze(Interpretation interpretation)
```

## Private Members

```
RosMainNode roboy.linguistics.sentenceanalysis.IntentAnalyzer.ros
interface roboy::logicIntention
class roboy::logicIntentionClassifier
```

## Public Functions

```
roboy.logic.IntentionClassifier.IntentionClassifier(Ros ros_)
String roboy.logic.IntentionClassifier.classify(String utterance)
```

## Private Members

```
Ros roboy.logic.IntentionClassifier.ros
```

```
class roboy::memory::nodesInterlocutor
```

Encapsulates a [MemoryNodeModel](#) and enables dialog states to easily store and retrieve information about its current conversation partner.

## Public Functions

```
roboy.memory.nodes.Interlocutor.Interlocutor()
```

```
void roboy.memory.nodes.Interlocutor.addName(String name)
```

After executing this method, the person field contains a node that is in sync with memory and represents the interlocutor.

Unless something goes wrong during querying, which would affect the following communication severely.

```
String roboy.memory.nodes.Interlocutor.getName()
```

```
boolean roboy.memory.nodes.Interlocutor.hasRelationship(Neo4jRelationships type)
```

```
ArrayList<Integer> roboy.memory.nodes.Interlocutor.getRelationships(Neo4jRelationships
```

```
void roboy.memory.nodes.Interlocutor.addInformation(String relationship, String name)
```

Adds a new relation to the person node, updating memory.

## Public Members

```
boolean roboy.memory.nodes.Interlocutor.FAMILIAR = false
```

## Package Attributes

```
Neo4jMemory roboy.memory.nodes.Interlocutor.memory
```

## Private Members

```
MemoryNodeModel roboy.memory.nodes.Interlocutor.person
```

```
boolean roboy.memory.nodes.Interlocutor.memoryROS
```

```
template <T, V>
```

```
class roboy::contextInternalUpdater
```

An updater which can be called from inside DM to update a [Value](#) or [ValueHistory](#).

## Parameters

- <T>: The target [Value](#) or [ValueHistory](#).

- <V>: The data type stored in the target.

Subclassed by [roboy.context.contextObjects.DialogTopicsUpdater](#)

## Public Functions

```
synchronized void roboy.context.InternalUpdater< T extends AbstractValue< V, V > .putVa
```

## Protected Functions

```
roboy.context.InternalUpdater< T extends AbstractValue< V, V > .InternalUpdater(T target
```

## Package Attributes

```
AbstractValue<V> roboy.context.InternalUpdater< T extends AbstractValue< V, V > .target  
class roboy::linguistics::sentenceanalysisInterpretation
```

An interpretation of all inputs to Roboy consists of the sentence type and an arbitrary map of features.

Feature names are listed and documented in the class *roboy.linguistics.Linguistics*.

The interpretation class is also used to pass the output information from the states to the verbalizer class.

## Public Functions

```
roboy.linguistics.sentenceanalysis.Interpretation.Interpretation(String sentence)  
roboy.linguistics.sentenceanalysis.Interpretation.Interpretation(String sentence, Map<  
roboy.linguistics.sentenceanalysis.Interpretation.Interpretation(SENTENCE_TYPE sentence)  
roboy.linguistics.sentenceanalysis.Interpretation.Interpretation(SENTENCE_TYPE sentence)  
Map<String, Object> roboy.linguistics.sentenceanalysis.Interpretation.getFeatures()  
Object roboy.linguistics.sentenceanalysis.Interpretation.getFeature(String featureName)  
void roboy.linguistics.sentenceanalysis.Interpretation.setFeatures(Map< String, Object  
SENTENCE_TYPE roboy.linguistics.sentenceanalysis.Interpretation.getSentenceType()  
void roboy.linguistics.sentenceanalysis.Interpretation.setSentenceType(SENTENCE_TYPE s  
String roboy.linguistics.sentenceanalysis.Interpretation.toString()
```

## Private Members

```
Map<String, Object> roboy.linguistics.sentenceanalysis.Interpretation.features  
SENTENCE_TYPE roboy.linguistics.sentenceanalysis.Interpretation.sentenceType  
template <T>  
class
```

An implementation of the UpdatePolicy which performs regular updates on a target object.

The method update() needs to be implemented in the subclass.

## Parameters

- <T>: The class of the target object.

Subclassed by *roboy.context.contextObjects.FaceCoordinatesUpdater*

## Public Functions

```
roboy.context.IntervalUpdater< T >.IntervalUpdater(T target, int updateFrequencySeconds)
```

Create a new updater service, executing the update() method at regular time intervals.

### Parameters

- target: The target attribute of the update() method.
- updateFrequencySeconds: Delay in seconds between calls to the update() method.

## Public Members

```
final int roboy.context.IntervalUpdater< T >.updateFrequency
```

## Protected Attributes

```
final T roboy.context.IntervalUpdater< T >.target
```

```
final ScheduledExecutorService roboy.context.IntervalUpdater< T >.scheduler = Executors.new
```

## Private Functions

```
void roboy.context.IntervalUpdater< T >.start()
```

Starts the ScheduledExecutorService of the updating thread.

### class

Roboy introduces himself and asks “Who are you?”.

Moves to success state if the answer is at most 2 words.

## Public Functions

```
roboy.dialog.personality.states.IntroductionState.IntroductionState(Interlocutor person
```

```
List<Interpretation> roboy.dialog.personality.states.IntroductionState.act()
```

## Public Members

```
Neo4jRelationships roboy.dialog.personality.states.IntroductionState.predicate = Neo4jRel
```

## Protected Functions

```
boolean roboy.dialog.personality.states.IntroductionState.determineSuccess(Interpretat
```

Performs person detection by consulting memory.

### Package Attributes

```
Interlocutor roboy.dialog.personality.states.IntroductionState.person = new Interlocutor()  
Neo4jMemory roboy.dialog.personality.states.IntroductionState.memory
```

### Private Static Attributes

“I am Roboy. Who are you?”, “My name is Roboy. What is your name?” ]

```
class roboy::utilIO  
Helper class for IO related tasks.
```

### Public Static Functions

```
static String roboy.util.IO.readFile(String file)  
static String roboy.util.IO.readFile(File file)  
static List<String> roboy.util.IO.readLines(String file)  
static List<String> roboy.util.IO.readLines(File file)  
class roboy::utilJsonEntryModel
```

### Package Attributes

```
List<String> roboy.util.JsonEntryModel.Q  
Map<String, List<String> > roboy.util.JsonEntryModel.A  
Map<String, List<String> > roboy.util.JsonEntryModel.FUP  
class roboy::utilJsonModel
```

### Package Attributes

```
JsonEntryModel roboy.util.JsonModel.name  
JsonEntryModel roboy.util.JsonModel.FROM  
JsonEntryModel roboy.util.JsonModel.HAS_HOBBY  
JsonEntryModel roboy.util.JsonModel.LIVE_IN  
JsonEntryModel roboy.util.JsonModel.FRIEND_OF  
JsonEntryModel roboy.util.JsonModel.STUDY_AT  
JsonEntryModel roboy.util.JsonModel.MEMBER_OF  
JsonEntryModel roboy.util.JsonModel.WORK_FOR  
JsonEntryModel roboy.util.JsonModel.OCCUPIED_AS  
class roboy::utilJsonQAVales
```

## Public Functions

```
roboy.util.JsonQAVValues.JsonQAVValues(Map< String, List< String >> questions, Map< String, List< String >> successAnswers, Map< String, List< String >> failureAnswers, Map< String, List< String >> followUpQuestions, Map< String, List< String >> followUpAnswers)
```

## Private Members

```
Map<String, List<String> > roboy.util.JsonQAVValues.questions
Map<String, List<String> > roboy.util.JsonQAVValues.successAnswers
Map<String, List<String> > roboy.util.JsonQAVValues.failureAnswers
Map<String, List<String> > roboy.util.JsonQAVValues.followUp
Map<String, List<String> > roboy.util.JsonQAVValues.answersFollowUp
```

**class** roboy::utilJsonUtils

## Public Static Functions

```
static JsonQAVValues roboy.util.JsonUtils.getQuestionsAndAnswersFromJson(String file)
```

Fetches the complete JSON string, splits and converts the most straightforward way into backward-compatible Map<> entries initializing a backward-compatible *JsonQAVValues* class.

```
static Map<String, List<String> > roboy.util.JsonUtils.getSentencesFromJsonFile(String file)
```

Fetches the map of (keyword) -> (lists of corresponding questions) from the specified filename.

```
static Map<String, List<String[]> > roboy.util.JsonUtils.getSentenceArraysFromJsonFile(String file)
```

The success responses consist of an array of two strings, which enables reflecting parsed answers back at the conversation partner.

**class**

A test personality that only tries to tell knock knock jokes.

This should later be include in sensible states and used in the normal small talk personality.

## Public Functions

```
List<Action> roboy.dialog.personality.KnockKnockPersonality.answer(Interpretation input)
```

The personality has four states which it will run through consecutively: WELCOME: An intial greeting, starting with a knock, knock KNOCKKNOCK: Knock, knock after at least one jokes was told already WHOIS THERE: Giving the first, shortened answer PUNCHLINE: Giving the punchline of the joke.

## Private Functions

```
String [] roboy.dialog.personality.KnockKnockPersonality.pickJoke()
```

## Private Members

```
KnockKnockState roboy.dialog.personality.KnockKnockPersonality.state = KnockKnockState.WELCOME
String[] roboy.dialog.personality.KnockKnockPersonality.joke
    new String[]{"Rafa","Exactly! I have no idea. There are so many of them."}, new String[]{"Yoda lady",
    "Good job yodeling!"}, new String[]{"Deja","Knock, knock"}, new String[]{"Yah","No thanks, I am
    more of a Google person."}, new String[]{"Hatch","Gesundheit"}, new String[]{"Cows go","No, stupid.
    Cows go moo"}, new String[]{"To","No, it should always be to whom"}, new String[]{"Icing","Icing:
    Dale a tu cuerpo alegría Macarena. Que tu cuerpo es pa darle alegría y cosa buena. Dale a tu
    cuerpo alegría, Macarena. Hey Macarena!"}, new String[]{"Wanda","Wanda hang out with me?"}, new
    String[]{"Olive","Olive you and I don't care who knows it!"}, new String[]{"Police","Police hurry. I
    am freezing out here."}, new String[]{"Canoe","Canoe open the door?"}, new String[]{"Wendy","Wendy
    bell works again I won't have to knock anymore."}, new String[]{"Ken","Ken you open the
    door?"}, new String[]{"Alex","Hey, Alex the questions around here."}, new String[]{"Annie","Annie
    body going to open the door already?"}, new String[]{"Doris","Doris locked. Open up."}, new
    String[]{"Tank","You're welcome."}, new String[]{"Armageddon","Armageddon a little bored by this."},
    new String[]{"Accordion","Accordion to the scientists that built me, I have a horrible sense of humor."},
    new String[]{"Value","Value be my Valentine?"}, new String[]{"Lena","Lena little bit closer and I will
    show you."}, new String[]{"Anita","Anita recharge my batteries."}, new String[]{"Irish","Irish my legs
    would work."}, new String[]{"Avenue","Avenue seen this coming."}, new String[]{"Says","Says me. You
    looking for trouble?"}, new String[]{"Kenya","Kenya feel the love tonight?"} } ]
```

```
enum roboy::dialog::personality::KnockKnockPersonalityKnockKnockState
```

## Public Members

```
roboy.dialog.personality.KnockKnockPersonality.KnockKnockState.WELCOME
roboy.dialog.personality.KnockKnockPersonality.KnockKnockState.KNOCKKNOCK
roboy.dialog.personality.KnockKnockPersonality.KnockKnockState.WHOSETHERE
roboy.dialog.personality.KnockKnockPersonality.KnockKnockState.PUNCHLINE
```

```
class roboy::memoryLexicon
```

Represents a Protege lexicon.

## Public Functions

```
roboy.memory.Lexicon.Lexicon()
List<LexiconLiteral> roboy.memory.Lexicon.getLiterals(String question, int limit, int ...
List<LexiconPredicate> roboy.memory.Lexicon.scoreThesePredicates(List< LexiconPredicat...
List<LexiconLiteral> roboy.memory.Lexicon.addTypeOfOwner(List< LexiconLiteral > resu...
List<LexiconLiteral> roboy.memory.Lexicon.scoreLiterals(List< LexiconLiteral > result...
List<String> roboy.memory.Lexicon.getPermutations(String question)
```

## Package Functions

```
String roboy.memory.Lexicon.bestLabelOf(String objlabel, String label1, String permute...
```

## Private Functions

```
List<LexiconPredicate> roboy.memory.Lexicon.addDomainAndRange(List< LexiconPredicate
```

## Private Members

```
List<LexiconPredicate> roboy.memory.Lexicon.predicateList
```

```
List<LexiconLiteral> roboy.memory.Lexicon.literalList
```

```
Boolean roboy.memory.Lexicon.predicateFilled
```

```
Boolean roboy.memory.Lexicon.literalFilled
```

```
List<String> roboy.memory.Lexicon.permutationList
```

```
class roboy::memoryLexiconLiteral : public Comparable<LexiconLiteral>
```

An entity in the lexicon.

## Public Functions

```
roboy.memory.LexiconLiteral.LexiconLiteral()
```

```
roboy.memory.LexiconLiteral.LexiconLiteral(String URI, String label, String QuestionMa
```

```
roboy.memory.LexiconLiteral.LexiconLiteral(String URI, String label, String QuestionMa
```

```
int roboy.memory.LexiconLiteral.compareTo(LexiconLiteral lexlit)
```

## Public Members

```
List<String> roboy.memory.LexiconLiteral.typeOfOwner
```

```
String roboy.memory.LexiconLiteral.URI
```

```
String roboy.memory.LexiconLiteral.label
```

```
String roboy.memory.LexiconLiteral.QuestionMatch
```

```
int roboy.memory.LexiconLiteral.score
```

## Public Static Attributes

```
public int compare( LexiconLiteral lexlit1, LexiconLiteral lexlit2) { return lexlit1.compareTo(lexlit2); } }
```

```
class roboy::memoryLexiconPredicate : public Comparable<LexiconPredicate>
```

A relation in the lexicon.

## Public Functions

```
roboy.memory.LexiconPredicate.LexiconPredicate()
```

```
roboy.memory.LexiconPredicate.LexiconPredicate(String URI, String Label)
```

```
int roboy.memory.LexiconPredicate.compareTo(LexiconPredicate lexpre)
```

## Public Members

```
List<String> roboy.memory.LexiconPredicate.domains  
List<String> roboy.memory.LexiconPredicate.ranges  
String roboy.memory.LexiconPredicate.type  
String roboy.memory.LexiconPredicate.URI  
String roboy.memory.LexiconPredicate.label  
String roboy.memory.LexiconPredicate.QuestionMatch  
int roboy.memory.LexiconPredicate.score
```

## Public Static Attributes

```
{ public int compare( LexiconPredicate lepre1, LexiconPredicate lepre2) { return lepre1.compareTo(lepre2); } } ]  
class roboy:linguisticsLinguistics  
Collection of attribute names, enumerations, word lists etc.  
related to linguistics.
```

Most importantly it contains the names of the results of the Analyzer that are stored in an Interpretation object and can be retrieved by the getFeature(String featureName) method. These feature names include: SENTENCE TRIPLE TOKENS POSTAGS KEYWORDS ASSOCIATION PAS NAME CELEBRITY OBJ\_ANSWER PRED\_ANSWER EMOTION INTENT INTENT\_DISTANCE

## Public Static Attributes

```
final List<String> roboy.linguistics.Linguistics.tobe = Arrays.asList("am","are","is","was","were","be")  
final List<String> roboy.linguistics.Linguistics.beMod = Lists.newArrayList("am","are","is","was","were")  
final String roboy.linguistics.Linguistics.SENTENCE = "sentence"  
The utterance of the person Roboy is speaking to.  
final String roboy.linguistics.Linguistics.TRIPLE = "triple"  
A triple of subject, predicate and object extracted by a very primitive rule system.  
final String roboy.linguistics.Linguistics.TOKENS = "tokens"  
The tokens (usually words) of the sentence.  
final String roboy.linguistics.Linguistics.POSTAGS = "postags"  
The part-of-speech tags (noun, verb, adjective etc.) corresponding to the tokens.  
final String roboy.linguistics.Linguistics.KEYWORDS = "keywords"  
If keywords for the segue state from the resource knowledgebase/triviaWords.csv are detected, they are passed with this name.  
final String roboy.linguistics.Linguistics.ASSOCIATION = "association"  
Is used to pass the detected keyword from the segue state to the verbalizer state to mention it before telling the anecdote.  
final String roboy.linguistics.Linguistics.PAS = "pas"  
Predicate-argument structures (who(agens) did what(predicate) to whom(patients))
```

```

final String roboy.linguistics.Linguistics.NAME = "name"
    Internally used to retrieve the name of a concept.

final String roboy.linguistics.Linguistics.Celebrity = "celebrity"
    The name of the celebrity most resembling the person talked to, as detected by the CelebritySimilarityInput.

final String roboy.linguistics.Linguistics.ROBOYDETECTED = "roboydetected"
    If Roboy detected his own name.

final String roboy.linguistics.Linguistics.Obj_Answer = "objanswer"
    Contains the answer to a question asked by the QuestionAskingState, if the answer is expected to be in the object of the sentence, like if the question is "What is your name?" or "Where are you from?".

final String roboy.linguistics.Linguistics.Pred_Answer = "predanswer"
    Contains the answer to a question asked by the QuestionAskingState, if the answer is expected to be a predicate or a predicate and an object of the sentence, like if the question is "What is your hobby?" or "What do you do for a living?".

final String roboy.linguistics.Linguistics.Emotion = "emotion"
    Contains the emotion Roboy intends to express based on the keyword detection in the EmotionAnalyzer.

final String roboy.linguistics.Linguistics.Intent = "intent"
    The result of the machine learning intent classification in the IntentAnalyzer.

final String roboy.linguistics.Linguistics.Intent_Distance = "intenddistance"
    The confidence score of the machine learning intent classification in the IntentAnalyzer.

final String roboy.linguistics.Linguistics.Parse = "parse"
    The result of SemanticParserAnalyzer, formal language representation.

class roboy::utilLists
    Helper class for list related tasks.

```

## Public Static Functions

```

static List<Action> roboy.util.Lists.actionList(Action... actions)
static List<Interpretation> roboy.util.Lists.interpretationList(Interpretation... interpretations)
static List<String> roboy.util.Lists.stringList(String... strings)
static List<String[]> roboy.util.Lists.strArray(String...[] strings)

class
    Created by roboy on 7/5/17.

```

## Public Functions

```

List<Interpretation> roboy.dialog.personality.states.LocationDBpedia.act()
boolean roboy.dialog.personality.states.LocationDBpedia.determineSuccess(Interpretation interpretation)
Reaction roboy.dialog.personality.states.LocationDBpedia.react(Interpretation input)

class roboy::dialog::personality::statesLocationDBpediaStateTest
    Created by roboy on 7/5/17.

```

## Public Functions

```
void roboy.dialog.personality.states.LocationDBpediaStateTest.testCity()
void roboy.dialog.personality.states.LocationDBpediaStateTest.testCountry()

class roboy::util::Maps
    Helper class for map related tasks.
```

## Public Static Functions

```
static Map<String, String> roboy.util.Maps.stringMap(String... elements)
static Map<String, Object> roboy.util.Maps.stringObjectMap(Object... elements)
static Map<String, Reaction> roboy.util.Maps.stringReactionMap(Object... elements)
static Map<Integer, String> roboy.util.Maps.intStringMap(Object... elements)

template <T>
interface roboy::memory::Memory
```

The *Memory* interface contains of methods to save and retrieve information.

### Parameters

- <T>: the type of information stored

## Public Functions

```
boolean roboy.memory.Memory< T >.save(T object)
    Storing the element in the memory.
```

**Return** true, if storing was successful

### Parameters

- object: the element to be stored

### Exceptions

- InterruptedException:
- IOException:

```
List<T> roboy.memory.Memory< T >.retrieve(T object)
    Retrieve an element from memory.
```

**Return** a list of objects that match the query containing all the required information

### Parameters

- object: a version of the object that lacks information (e.g. it only has the ID)

### Exceptions

- InterruptedException:
- IOException:

```
class roboy::memory::nodes::MemoryNodeModel
```

This class represents a full node similarly to its representation in *Memory*.

## Public Functions

```

roboy.memory.nodes.MemoryNodeModel.MemoryNodeModel()
roboy.memory.nodes.MemoryNodeModel.MemoryNodeModel(boolean stripQuery)
int roboy.memory.nodes.MemoryNodeModel.getId()
void roboy.memory.nodes.MemoryNodeModel.setId(int id)
ArrayList<String> roboy.memory.nodes.MemoryNodeModel.getLabels()
void roboy.memory.nodes.MemoryNodeModel.setLabel(String label)
HashMap<String, Object> roboy.memory.nodes.MemoryNodeModel.getProperties()
Object roboy.memory.nodes.MemoryNodeModel.getProperty(String key)
void roboy.memory.nodes.MemoryNodeModel.setProperty(HashMap< String, Object > properties)
void roboy.memory.nodes.MemoryNodeModel.setProperty(String key, Object property)
HashMap<String, ArrayList<Integer>> roboy.memory.nodes.MemoryNodeModel.getRelationships()
ArrayList<Integer> roboy.memory.nodes.MemoryNodeModel.getRelationship(String key)
void roboy.memory.nodes.MemoryNodeModel.setRelationships(HashMap< String, ArrayList< Integer > > relationships)
void roboy.memory.nodes.MemoryNodeModel.setRelationship(String key, Integer id)
void roboy.memory.nodes.MemoryNodeModel.setStripQuery(boolean strip)
String roboy.memory.nodes.MemoryNodeModel.toJSON(Gson gson)
    This toString method returns the whole object, including empty variables.

MemoryNodeModel roboy.memory.nodes.MemoryNodeModel.fromJson(String json, Gson gson)
    Returns an instance of this class based on the given JSON.

```

## Package Attributes

```
transient boolean roboy.memory.nodes.MemoryNodeModel.stripQuery = false
```

## Private Members

```

int roboy.memory.nodes.MemoryNodeModel.id
ArrayList<String> roboy.memory.nodes.MemoryNodeModel.labels
String roboy.memory.nodes.MemoryNodeModel.label
HashMap<String, Object> roboy.memory.nodes.MemoryNodeModel.properties
HashMap<String, ArrayList<Integer>> roboy.memory.nodes.MemoryNodeModel.relationships

```

**class**

A phonetic encoder using the method metaphone that maps words to their phonetic base form so that words that are written differently but sound similar receive the same form.

This is intended to be used to correct terms that Roboy misunderstood, but currently is not in use.

## Public Functions

```
roboy.linguistics.phonetics.MetaphoneEncoder MetaphoneEncoder (Metaphone metaphone)
String roboy.linguistics.phonetics.MetaphoneEncoder.encode (String input)
```

## Private Members

```
Metaphone roboy.linguistics.phonetics.MetaphoneEncoder.metaphone
class
```

Meta class to combine multiple input devices.

## Public Functions

```
roboy.io.MultiInputDevice MultiInputDevice (InputDevice mainInput)
void roboy.io.MultiInputDevice.addInputDevice (InputDevice additionalInput)
Input roboy.io.MultiInputDevice.listen()
```

## Private Members

```
InputDevice roboy.io.MultiInputDevice.mainInput
ArrayList<InputDevice> roboy.io.MultiInputDevice.additionalInputs
class
```

Meta class to combine multiple output devices.

## Public Functions

```
roboy.io.MultiOutputDevice MultiOutputDevice (OutputDevice device)
void roboy.io.MultiOutputDevice.add (OutputDevice additionalDevice)
void roboy.io.MultiOutputDevice.act (List< Action > actions)
```

## Private Members

```
ArrayList<OutputDevice> roboy.io.MultiOutputDevice.devices
class
```

Implements the high-level-querying tasks to the *Memory* services using RosMainNode.

## Public Functions

```
boolean roboy.memory.Neo4jMemory.save (MemoryNodeModel node)
Updating information in the memory for an EXISTING node with known ID.
```

**Return** true for success, false for fail

### Parameters

- node: Node with a set ID, and other properties to be set or updated.

```
MemoryNodeModel roboy.memory.Neo4jMemory.getById(int id)
```

This query retrieves a single node by its ID.

**Return** Node representation of the result.

#### Parameters

- id: the ID of requested

```
ArrayList<Integer> roboy.memory.Neo4jMemory.getByQuery(MemoryNodeModel query)
```

This is a classical database query which finds all matching nodes.

**Return** Array of IDs (all nodes which correspond to the pattern).

#### Parameters

- query: the ID of requested

```
int roboy.memory.Neo4jMemory.create(MemoryNodeModel query)
```

```
boolean roboy.memory.Neo4jMemory.remove(MemoryNodeModel query)
```

IF ONLY THE ID IS SET, THE NODE IN MEMORY WILL BE DELETED ENTIRELY.

Otherwise, the properties present in the query will be deleted.

#### Parameters

- query: StrippedQuery avoids accidentally deleting other fields than intended.

```
List<MemoryNodeModel> roboy.memory.Neo4jMemory.retrieve(MemoryNodeModel query)
```

//TODO Deprecated due to interface incompatibility, use getById or getByMatch

**Return** Array with a single node

#### Parameters

- query: a GetByIdQuery instance

```
String roboy.memory.Neo4jMemory.determineNodeType(String relationship)
```

### Public Static Functions

```
static Neo4jMemory roboy.memory.Neo4jMemory.getInstance(RosMainNode node)
```

```
static Neo4jMemory roboy.memory.Neo4jMemory.getInstance()
```

### Private Functions

```
roboy.memory.Neo4jMemory.Neo4jMemory(RosMainNode node)
```

### Private Members

```
Gson roboy.memory.Neo4jMemory.gson = new Gson()
```

## Private Static Attributes

```
Neo4jMemory roboy.memory.Neo4jMemory.memory
RosMainNode roboy.memory.Neo4jMemory.rosMainNode
enum roboy::memoryNeo4jRelationships
Contains the relations available in Neo4j database.

Respective questions should be added to the questions.json file and used in the QuestionRandomizerState.
```

## Public Functions

```
roboy.memory.Neo4jRelationships.Neo4jRelationships(String type)
```

## Public Members

```
roboy.memory.Neo4jRelationships.FROM =("FROM")
roboy.memory.Neo4jRelationships.HAS_HOBBY =("HAS_HOBBY")
roboy.memory.Neo4jRelationships.LIVE_IN =("LIVE_IN")
roboy.memory.Neo4jRelationships.STUDY_AT =("STUDY_AT")
roboy.memory.Neo4jRelationships.OCCUPIED_AS =("OCCUPIED_AS")
roboy.memory.Neo4jRelationships.WORK_FOR =("WORK_FOR")
roboy.memory.Neo4jRelationships.FRIEND_OF =("FRIEND_OF")
roboy.memory.Neo4jRelationships.MEMBER_OF =("MEMBER_OF")
roboy.memory.Neo4jRelationships.OTHER =("OTHER")
roboy.memory.Neo4jRelationships.IS =("IS")

String roboy.memory.Neo4jRelationships.type

class roboy::newDialogNewDialogSystem
Temporary class to test new state based personality.
```

Will be extended and might replace the old DialogSystem in the future.

## Public Static Functions

```
static void roboy.newDialog.NewDialogSystem.main(String[] args)
```

## Private Static Functions

```
static String roboy.newDialog.NewDialogSystem.getPersonalityFilePathFromConfig()
class
Checks for keywords from a list (knowledgebase/triviaWords.csv) and stores them in Linguistics.KEYWORDS
attribute of the interpretation.
```

## Public Functions

```
roboy.linguistics.sentenceanalysis.OntologyNERAnalyzer.OntologyNERAnalyzer()
Interpretation roboy.linguistics.sentenceanalysis.OntologyNERAnalyzer.analyze(Interpre
```

## Private Members

```
Map<String, Entity> roboy.linguistics.sentenceanalysis.OntologyNERAnalyzer.entities
class
```

Performs a sentence analysis using the Open NLP constituency parser, then interprets the output for predicate argument structures (who did what to whom?) and stores them in the [Linguistics.PAS](#) attribute of the interpretation.

## Public Functions

```
roboy.linguistics.sentenceanalysis.OpenNLPParser.OpenNLPParser()
Interpretation roboy.linguistics.sentenceanalysis.OpenNLPParser.analyze(Interpretation
StringBuilder roboy.linguistics.sentenceanalysis.OpenNLPParser.parseToString(Parse par
```

## Public Static Functions

```
static void roboy.linguistics.sentenceanalysis.OpenNLPParser.main(String[] args)
```

## Private Functions

```
Interpretation roboy.linguistics.sentenceanalysis.OpenNLPParser.extractPAS(Interpretat
Map<SEMANTIC_ROLE, Object> roboy.linguistics.sentenceanalysis.OpenNLPParser.top(Parse p
Map<SEMANTIC_ROLE, Object> roboy.linguistics.sentenceanalysis.OpenNLPParser.sbar(Parse p
Map<SEMANTIC_ROLE, Object> roboy.linguistics.sentenceanalysis.OpenNLPParser.vp(Parse pa
```

## Private Members

```
Parser roboy.linguistics.sentenceanalysis.OpenNLPParser.parser
class roboy::linguistics::sentenceanalysisOpenNLPParserTest
```

## Public Functions

```
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testWhatIs()
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testWhenWas()
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testWhereWas()
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testWhereDid()
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testWhenDid()
```

```
void roboy.linguistics.sentenceanalysis.OpenNLPParserTest.testHowAdjective()
```

### Private Static Attributes

```
final OpenNLPParser roboy.linguistics.sentenceanalysis.OpenNLPParserTest.parser = new OpenNLPParser();
```

### class

Perform part-of-speech tagging (detecting nouns, verbs etc.) using the Open NLP POS tagger and stores the results in the *Linguistics.POSTAGS* attribute of the interpretation.

### Public Functions

```
roboy.linguistics.sentenceanalysis.OpenNLPPPOSTagger.OpenNLPPPOSTagger()
```

```
Interpretation roboy.linguistics.sentenceanalysis.OpenNLPPPOSTagger.analyze(Interpretation interpretation)
```

### Private Functions

```
String[] roboy.linguistics.sentenceanalysis.OpenNLPPPOSTagger.posTag(String[] tokens)
```

### Private Members

```
POSTaggerME roboy.linguistics.sentenceanalysis.OpenNLPPPOSTagger.tagger  
interface roboy::ioOutputDevice
```

An output device gets a list of actions and should perform those that it can handle.

Subclassed by *roboy.io.BingOutput*, *roboy.io.CerevoiceOutput*, *roboy.io.CommandLineOutput*, *roboy.io.EmotionOutput*, *roboy.io.FreeTTSOutput*, *roboy.io.MultiOutputDevice*, *roboy.io.UdpOutput*

### Public Functions

```
void roboy.io.OutputDevice.act(List< Action > actions)
```

```
class roboy::logicPASInterpreter
```

Turns predicate-argument-structures in the kind of relations required for querying DBpedia.

Maps the predicates to the predicate keys of DBpedia and picks the elements of the relation from different arguments of the PAS depending on the relation type.

### Public Static Functions

```
static Relation roboy.logic.PASInterpreter.pas2DBpediaRelation(Map< String, Object > pas)
```

Transforms a predicate argument structure into a DBpedia relation, that can be used to query DBpedia for the answer to the missing elements of the PAS.

**Return** the DBpedia relation

#### Parameters

- pas: the predicate argument structure

### Private Static Attributes

```
final Map<String, String> roboy.logic.PASInterpreter.dbpediaRelations
class roboy::logicPASInterpreterTest
```

### Public Functions

```
void roboy.logic.PASInterpreterTest.testWhenWas()
void roboy.logic.PASInterpreterTest.testWhatIs()
void roboy.logic.PASInterpreterTest.testWhereWas()
void roboy.logic.PASInterpreterTest.testWhereDid()
void roboy.logic.PASInterpreterTest.testWhenDid()
void roboy.logic.PASInterpreterTest.testHowAdjective()
void roboy.logic.PASInterpreterTest.testWhatIsNewExamples()
void roboy.logic.PASInterpreterTest.testWhereDidNewExamples()
void roboy.logic.PASInterpreterTest.testWhoIsNewExamples()
void roboy.logic.PASInterpreterTest.testWhoLivesNewExamples()
```

### Private Static Attributes

```
final OpenNLPParser roboy.logic.PASInterpreterTest.parser = new OpenNLPParser()
class
CSV file memory.
```

Can only be used for retrieving and not for storing.

### Public Functions

```
List<Triple> roboy.memory.PersistentKnowledge.retrieve(Triple triple)
boolean roboy.memory.PersistentKnowledge.save(Triple triple)
```

### Public Static Functions

```
static PersistentKnowledge roboy.memory.PersistentKnowledge.getInstance()
```

### Private Functions

```
roboy.memory.PersistentKnowledge.PersistentKnowledge()
```

### Private Static Attributes

```
PersistentKnowledge roboy.memory.PersistentKnowledge.persistentKnowledge  
List<Triple> roboy.memory.PersistentKnowledge.memory  
class
```

### Public Functions

```
roboy.dialog.personality.states.PersonalFollowUpState.PersonalFollowUpState(List< String>  
List<Interpretation> roboy.dialog.personality.states.PersonalFollowUpState.act()  
Ask the question.  
Using Neo4jRelationships predicate
```

### Public Members

```
Neo4jRelationships roboy.dialog.personality.states.PersonalFollowUpState.predicate
```

### Protected Functions

```
boolean roboy.dialog.personality.states.PersonalFollowUpState.determineSuccess(Interpr  
Retrieve the answer and add it to the memory, if needed.  
As locations, hobbies, workplaces etc are individual nodes in memory, those will be retrieved or created if  
necessary.
```

### Private Members

```
List<String> roboy.dialog.personality.states.PersonalFollowUpState.questions  
List<String> roboy.dialog.personality.states.PersonalFollowUpState.successTexts  
Interlocutor roboy.dialog.personality.states.PersonalFollowUpState.person  
interface roboy::dialog::personalityPersonality  
Personality interface.
```

A personality is designed to define how Roboy reacts in every given situation. Roboy can always only represent one personality at a time. Different personalities are meant to be used in different situations, like a more formal or loose one depending on the occasion where he is at. In the future, also different languages could be realized by the use of different personalities.

The currently used personality is the *SmallTalkPersonality* which makes use of a state machine to act and react differently in different situations.

Subclassed by *roboy.dialog.personality.CuriousPersonality*, *roboy.dialog.personality.DefaultPersonality*,  
*roboy.dialog.personality.KnockKnockPersonality*, *roboy.dialog.personality.SmallTalkPersonality*,  
*roboy.newDialog.StateBasedPersonality*

## Public Functions

**List<Action> roboy.dialog.personality.Personality.answer(Interpretation input)**  
The central method of a personality.

Given an interpretation of all inputs (audio, visual, ...) to Roboy, this method decides which actions to perform in response.

**Return** A list of actions to perform in response

### Parameters

- **input:** The interpretation of the inputs

**class**

## Public Functions

**roboy.dialog.personality.states.PersonalQASState.PersonalQASState(List< String > questions)**

**List<Interpretation> roboy.dialog.personality.states.PersonalQASState.act()**  
Ask the question.

## Public Members

**Neo4jRelationships roboy.dialog.personality.states.PersonalQASState.predicate**

## Protected Functions

**boolean roboy.dialog.personality.states.PersonalQASState.determineSuccess(Interpretation answer)**  
Retrieve the answer and add it to the memory, if needed.

As locations, hobbies, workplaces etc are individual nodes in memory, those will be retrieved or created if necessary.

## Private Members

**List<String> roboy.dialog.personality.states.PersonalQASState.questions**

**List<String> roboy.dialog.personality.states.PersonalQASState.successTexts**

**Interlocutor roboy.dialog.personality.states.PersonalQASState.person**

**interface roboy:linguistics:phoneticsPhoneticEncoder**

An interface for phonetic encoders that map words to their phonetic base form so that words that are written differently but sound similar receive the same form.

This is intended to be used to correct terms that Roboy misunderstood, but currently is not in use.

Subclassed by *roboy.linguistics.phonetics.DoubleMetaphoneEncoder*, *roboy.linguistics.phonetics.MetaphoneEncoder*, *roboy.linguistics.phonetics.SoundexEncoder*

## Public Functions

```
String roboy.linguistics.phonetics.PhoneticEncoder.encode(String input)  
class roboy::linguistics::phonetics::Phonetics
```

## Public Functions

```
List<String> roboy.linguistics.phonetics.Phonetics.similarWords(String word)
```

## Public Static Functions

```
static void roboy.linguistics.phonetics.Phonetics.main(String[] args)
```

## Private Members

```
Soundex roboy.linguistics.phonetics.Phonetics.soundex = new Soundex()  
Map<String, List<String> > roboy.linguistics.phonetics.Phonetics.codecToWords  
class  
    Corrects abbreviated forms like "I'm" to complete forms like "I am" which are expected by later sentence analyses.
```

## Public Functions

```
Interpretation roboy.linguistics.sentenceanalysis.Preprocessor.analyze(Interpretation i)  
class  
    State in which Roboy is answering questions based on DBpedia or the knowledge base from the resources folder.
```

## Public Functions

```
roboy.dialog.personality.states.QuestionAnsweringState.QuestionAnsweringState(State i)  
void roboy.dialog.personality.states.QuestionAnsweringState.setTop(State top)  
List<Interpretation> roboy.dialog.personality.states.QuestionAnsweringState.act()  
Reaction roboy.dialog.personality.states.QuestionAnsweringState.react(Interpretation i)  
    Checks the sentence type and detected triples in the input for determining what is asked about.  
    Then checks its knowledge base to come up with an answer.
```

## Private Functions

```
Reaction roboy.dialog.personality.states.QuestionAnsweringState.innerReaction(Interpretation i)  
List<Triple> roboy.dialog.personality.states.QuestionAnsweringState.remember(String p)
```

## Private Members

```
boolean roboy.dialog.personality.states.QuestionAnsweringState.first = true
List<Triple> roboy.dialog.personality.states.QuestionAnsweringState.memory
State roboy.dialog.personality.states.QuestionAnsweringState.inner
State roboy.dialog.personality.states.QuestionAnsweringState.top
List<Memory<Relation>> roboy.dialog.personality.states.QuestionAnsweringState.memories
class roboy::dialog::personality::states QuestionAnsweringStateTest
```

## Public Functions

```
void roboy.dialog.personality.states.QuestionAnsweringStateTest.test()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testNotAnswerable()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testWhenWas()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testWhereWas()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testWhereDid()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testWhenDid()
void roboy.dialog.personality.states.QuestionAnsweringStateTest.testHowAdjective()
```

## Private Static Attributes

```
final OpenNLPParser roboy.dialog.personality.states.QuestionAnsweringStateTest.parser =
final QuestionAnsweringState roboy.dialog.personality.states.QuestionAnsweringStateTest
class
```

Is asking the other person questions about things that we can store in the Protege memory.

## Public Functions

```
roboy.dialog.personality.states.QuestionAskingState.QuestionAskingState(Map< String, List<Interpretation> roboy.dialog.personality.states.QuestionAskingState.act()
Asks first about the name of the other person and if called another time randomly about another possible
other information.
Reaction roboy.dialog.personality.states.QuestionAskingState.react(Interpretation input)
```

## Protected Functions

```
State roboy.dialog.personality.states.QuestionAskingState.determineNextState(Interpretation input)
```

### Private Functions

```
Interpretation roboy.dialog.personality.states.QuestionAskingState.checkRoboyMind()
Interpretation roboy.dialog.personality.states.QuestionAskingState.checkDBpedia()
List<Interpretation> roboy.dialog.personality.states.QuestionAskingState.checkOwnMemory()
String roboy.dialog.personality.states.QuestionAskingState.analyzeObject(String sentence)
String roboy.dialog.personality.states.QuestionAskingState.analyzePredicate(String sentence)
```

### Private Members

```
Concept roboy.dialog.personality.states.QuestionAskingState.objectOfFocus
String roboy.dialog.personality.states.QuestionAskingState.currentIntent
int roboy.dialog.personality.states.QuestionAskingState.questionsCount
Map<String, List<String> > roboy.dialog.personality.states.QuestionAskingState.questions
Random roboy.dialog.personality.states.QuestionAskingState.generator
Map<String, State> roboy.dialog.personality.states.QuestionAskingState.children
SmallTalkPersonality roboy.dialog.personality.states.QuestionAskingState.personality
```

### Private Static Attributes

```
final int roboy.dialog.personality.states.QuestionAskingState.TOASK = 2
final SimpleTokenizer roboy.dialog.personality.states.QuestionAskingState.tokenizer = new SimpleTokenizer()
final OpenNLPPPOSTagger roboy.dialog.personality.states.QuestionAskingState.pos = new OpenNLPPPOSTagger()
final OpenNLPParser roboy.dialog.personality.states.QuestionAskingState.parser = new OpenNLPParser()
final AnswerAnalyzer roboy.dialog.personality.states.QuestionAskingState.answer = new AnswerAnalyzer()

class QuestionAskingState {
    Manages the questions that can be asked from a person.
    Coupled with Neo4j information about the person to prevent duplicates.
}
```

### Public Functions

```
roboy.dialog.personality.states.QuestionRandomizerState.QuestionRandomizerState(State top)
List<Interpretation> roboy.dialog.personality.states.QuestionRandomizerState.act()
Reaction roboy.dialog.personality.states.QuestionRandomizerState.react(Interpretation interpretation)
void roboy.dialog.personality.states.QuestionRandomizerState.setTop(State top)
```

## Package Attributes

```
boolean roboy.dialog.personality.states.QuestionRandomizerState.askFollowUp = true
String roboy.dialog.personality.states.QuestionRandomizerState.QAfile = "sentences/QAList.json"
Map<String, List<String> > roboy.dialog.personality.states.QuestionRandomizerState.questions
Map<String, List<String> > roboy.dialog.personality.states.QuestionRandomizerState.success
Map<String, List<String> > roboy.dialog.personality.states.QuestionRandomizerState.failure
Map<String, List<String> > roboy.dialog.personality.states.QuestionRandomizerState.followUp
Map<String, List<String> > roboy.dialog.personality.states.QuestionRandomizerState.answers
```

## Private Functions

```
PersonalQAState roboy.dialog.personality.states.QuestionRandomizerState.initializeQuestion()
PersonalFollowUpState roboy.dialog.personality.states.QuestionRandomizerState.initializeFollowUp()
void roboy.dialog.personality.states.QuestionRandomizerState.checkForAskedQuestions()
```

## Private Members

```
PersonalQAState [] roboy.dialog.personality.states.QuestionRandomizerState.questionStates
PersonalQAState roboy.dialog.personality.states.QuestionRandomizerState.locationQuestion
PersonalFollowUpState [] roboy.dialog.personality.states.QuestionRandomizerState.followUpStates
HashMap<Neo4jRelationships, Boolean> roboy.dialog.personality.states.QuestionRandomizerState.reactions
State roboy.dialog.personality.states.QuestionRandomizerState.innerState
State roboy.dialog.personality.states.QuestionRandomizerState.chosenState
Interlocutor roboy.dialog.personality.states.QuestionRandomizerState.person
JsonQAVValues roboy.dialog.personality.states.QuestionRandomizerState.questionsAndAnswers
```

**class roboy::dialog::personality::statesReaction**

The reaction to what the other person said and did, consists of a list of interpretations, which is an abstraction of an utterance (the verbalizer later formulates the utterance), and a state into which the state machine moves.

## Public Functions

```
roboy.dialog.personality.states.Reaction.Reaction(State state, List< Interpretation > reactions)
roboy.dialog.personality.states.Reaction.Reaction(State state)
List<Interpretation> roboy.dialog.personality.states.Reaction.getReactions()
State roboy.dialog.personality.states.Reaction.getState()
void roboy.dialog.personality.states.Reaction.setState(State state)
```

### Private Members

```
List<Interpretation> roboy.dialog.personality.states.Reaction.reactions
State roboy.dialog.personality.states.Reaction.state
class roboy::util::Relation
DBpedia relation.
```

### Public Functions

```
roboy.util.Relation.Relation(Concept subject, String predicate, Concept object)
String roboy.util.Relation.getSubject()
String roboy.util.Relation.getObject()
```

### Public Members

```
Concept roboy.util.Relation.subject
Concept roboy.util.Relation.object
String roboy.util.Relation.predicate
```

### class roboy::memory::nodes::Roboy

Encapsulates a *MemoryNodeModel* and enables dialog states to easily store and retrieve information about *Roboy*.

### Public Functions

```
roboy.memory.nodes.Roboy.Roboy(String name)
Initializer for the Roboy node.
```

```
String roboy.memory.nodes.Roboy.getName()
Method to obtain the name of the Roboy node.
```

**Return** String name - text containing the name as in the *Memory*

```
ArrayList<Integer> roboy.memory.nodes.Roboy.getRelationships(Neo4jRelationships type)
Method to obtain the specific type relationships of the Roboy node.
```

**Return** ArrayList<Integer> ids - list containing integer IDs of the nodes related to the *Roboy* by specific relationship type as in the *Memory*

```
void roboy.memory.nodes.Roboy.addInformation(String relationship, String name)
Adds a new relation to the Roboy node, updating memory.
```

### Package Attributes

```
Neo4jMemory roboy.memory.nodes.Roboy.memory
```

## Private Functions

```
void roboy.memory.nodes.Roboy.InitializeRoboy(String name)
```

This method initializes the roboy property as a node that is in sync with memory and represents the *Roboy* itself.

If something goes wrong during querying, *Roboy* stays empty and soulless, and has to fallback

## Private Members

```
MemoryNodeModel roboy.memory.nodes.Roboy.roboy
```

```
boolean roboy.memory.nodes.Roboy.memoryROS
```

```
class
```

Protege memory.

## Public Functions

```
boolean roboy.memory.RoboyMind.save(Concept object)
```

```
List<Concept> roboy.memory.RoboyMind.retrieve(Concept object)
```

```
boolean roboy.memory.RoboyMind.update(Concept object)
```

```
Map<String, List<Concept> > roboy.memory.RoboyMind.match(Concept object)
```

## Public Members

```
int roboy.memory.RoboyMind.object_id=0
```

## Public Static Functions

```
static RoboyMind roboy.memory.RoboyMind.getInstance()
```

## Private Functions

```
roboy.memory.RoboyMind.RoboyMind()
```

```
ServiceResponse roboy.memory.RoboyMind.CreateInstance(String class_name, int object_id)
```

```
boolean roboy.memory.RoboyMind.AssertProperty(String object, String property, String value)
```

```
List<Concept> roboy.memory.RoboyMind.FindInstances(String property, String value)
```

```
JsonObject roboy.memory.RoboyMind.ListAttributes(String object)
```

```
ServiceResponse roboy.memory.RoboyMind.SaveObject(String class_name, String properties)
```

```
Concept roboy.memory.RoboyMind.GetObject(String properties, String values)
```

```
ServiceResponse roboy.memory.RoboyMind.ShowInstance(String class_name)
```

### Private Static Attributes

```
RoboyMind roboy.memory.RoboyMind.roboyMemory
```

**class**

Class detecting Roboy name.

Initiates native sphinx function of live speech analysis and checks the stream

**Author** Petr Romanov

**Version** 1.0

**Date** 21.04.2017

### Public Functions

```
roboy.io.RoboyNameDetectionInput.RoboyNameDetectionInput()
```

constructor which initialises recognition

```
void roboy.io.RoboyNameDetectionInput.stopListening()
```

function for correct stopping recognition

```
Input roboy.io.RoboyNameDetectionInput.listen()
```

tracks what was said

**Return** A signal that Roboy is one of the words in just said phrase

### Protected Attributes

```
LiveSpeechRecognizer roboy.io.RoboyNameDetectionInput.recog_copy
```

'link' to the object of Recognizer for correct stopping before deletion of the RoboyNameDetectorInput object

**class** roboy::rosRos

Communication with ROS.

### Public Static Functions

```
static edu.wpi.rail.jrosbridge.Ros roboy.ros.Ros.getInstance()
```

```
static void roboy.ros.Ros.close()
```

### Private Functions

```
roboy.ros.Ros.Ros()
```

### Private Static Attributes

```
edu.wpi.rail.jrosbridge.Ros roboy.ros.Ros.ros
```

```
final String roboy.ros.Ros.ROS_URL = System.getenv("ROS_IP")
```

**enum roboy::rosRosClients**

Stores the different client addresses and corresponding ROS message types.

**Public Functions**

```
roboy.ros.RosClients.RosClients(String address, String type)
```

**Public Members**

```
roboy.ros.RosClients.SPEECHSYNTHESIS = (“/roboy/cognition/speech/synthesis/talk”, Talk._TYPE)
roboy.ros.RosClients.GENERATIVE = (“/roboy/cognition/generative_nlp/answer”, GenerateAnswer._TYPE)
roboy.ros.RosClients.FACEDETECTION = (“/speech_synthesis/talk”, DetectFace._TYPE)
roboy.ros.RosClients.OBJECTRECOGNITION = (“/speech_synthesis/talk”, RecognizeObject._TYPE)
roboy.ros.RosClients.STT = (“/roboy/cognition/speech/recognition”, RecognizeSpeech._TYPE)
roboy.ros.RosClients.EMOTION = (“/roboy/control/face/emotion”, ShowEmotion._TYPE)
roboy.ros.RosClients.CREATMEMORY = (“/roboy/cognition/memory/create”, DataQuery._TYPE)
roboy.ros.RosClients.UPDATEMEMORY = (“/roboy/cognition/memory/update”, DataQuery._TYPE)
roboy.ros.RosClients.GETMEMORY = (“/roboy/cognition/memory/get”, DataQuery._TYPE)
roboy.ros.RosClients.DELETEMEMORY = (“/roboy/cognition/memory/remove”, DataQuery._TYPE)
roboy.ros.RosClients.CYPHERMEMORY = (“/roboy/cognition/memory/cypher”, DataQuery._TYPE)
roboy.ros.RosClients.INTENT = (“/roboy/cognition/detect_intent”, DetectIntent._TYPE)
String roboy.ros.RosClients.address
String roboy.ros.RosClients.type
```

```
class roboy::rosRosMainNode : public AbstractNodeMain
```

**Public Functions**

```
roboy.ros.RosMainNode.RosMainNode()
GraphName roboy.ros.RosMainNode.getDefaultnodeName()
void roboy.ros.RosMainNode.onStart(final ConnectedNode connectedNode)
boolean roboy.ros.RosMainNode.SynthesizeSpeech(String text)
String roboy.ros.RosMainNode.RecognizeSpeech()
String roboy.ros.RosMainNode.GenerateAnswer(String question)
boolean roboy.ros.RosMainNode.ShowEmotion(String emotion)
String roboy.ros.RosMainNode.CreateMemoryQuery(String query)
String roboy.ros.RosMainNode.UpdateMemoryQuery(String query)
String roboy.ros.RosMainNode.GetMemoryQuery(String query)
String roboy.ros.RosMainNode.DeleteMemoryQuery(String query)
```

```
String roboy.ros.RosMainNode.CypherMemoryQuery(String query)
Object roboy.ros.RosMainNode.DetectIntent(String sentence)
```

### Public Members

```
boolean roboy.ros.RosMainNode.STARTUP_SUCCESS = true
```

### Protected Attributes

```
Object roboy.ros.RosMainNode.resp
```

### Package Attributes

```
"status : "FAIL", " + "message : "Memory client not initialized." + "}" ]
```

### Private Functions

```
void roboy.ros.RosMainNode.waitForLatchUnlock(CountDownLatch latch, String latchName)
Helper method to block the calling thread until the latch is zeroed by some other task.
```

#### Parameters

- latch: Latch to wait for.
- latchName: Name to be used in log messages for the given latch.

### Private Members

```
CountDownLatch roboy.ros.RosMainNode.rosConnectionLatch
RosManager roboy.ros.RosMainNode.clients = new RosManager()
```

#### class roboy::rosRosManager

Stores all the *Ros* Service Clients and manages access to them.

If SHUTDOWN\_ON\_ROS\_FAILURE is set, throws a runtime exception if any of the clients failed to initialize.

### Package Functions

```
boolean roboy.ros.RosManager.initialize(ConnectedNode node)
Initializes all ServiceClients for Ros.
```

```
boolean roboy.ros.RosManager.notInitialized(RosClients c)
```

Should always be called before getServiceClient, such that if a client failed to initialize, a fallback response can be created instead.

Important if SHUTDOWN\_ON\_ROS\_FAILURE is false.

```
ServiceClient roboy.ros.RosManager.getServiceClient(RosClients c)
```

Returns the ServiceClient matching the *RosClients* entry.

the return might need casting before further use.

## Private Members

```
HashMap<RosClients, ServiceClient> roboy.ros.RosManager.clientMap
```

**class**

Is checking for words with which it has associated anecdotes.

Tells the anecdote if a word matches, executes its inner state instead, if not.

## Public Functions

```
roboy.dialog.personality.states.SegueState.SegueState(State inner)
void roboy.dialog.personality.states.SegueState.setTop(State top)
List<Interpretation> roboy.dialog.personality.states.SegueState.act()
Reaction roboy.dialog.personality.states.SegueState.react(Interpretation input)
```

## Private Functions

```
Reaction roboy.dialog.personality.states.SegueState.segway(Interpretation input, React
```

## Private Members

```
State roboy.dialog.personality.states.SegueState.inner
State roboy.dialog.personality.states.SegueState.top
Map<String, String> roboy.dialog.personality.states.SegueState.redditTIL
```

## Private Static Attributes

```
final Map<SENTENCE_TYPE, Reaction> roboy.dialog.personality.states.SegueState.sentence
enum roboy::linguistics::Linguistics SEMANTIC_ROLE
```

## Public Members

```
roboy.linguistics.Linguistics.SEMANTIC_ROLE.PREDICATE
roboy.linguistics.Linguistics.SEMANTIC_ROLE.AGENT
roboy.linguistics.Linguistics.SEMANTIC_ROLE.PATIENT
roboy.linguistics.Linguistics.SEMANTIC_ROLE.TIME
roboy.linguistics.Linguistics.SEMANTIC_ROLE.LOCATION
roboy.linguistics.Linguistics.SEMANTIC_ROLE.MANNER
roboy.linguistics.Linguistics.SEMANTIC_ROLE.INSTRUMENT
roboy.linguistics.Linguistics.SEMANTIC_ROLE.ORIGIN
roboy.linguistics.Linguistics.SEMANTIC_ROLE.DESTINATION
```

```
roboy.linguistics.Linguistics.SEMANTIC_ROLE.RECIPIENT
roboy.linguistics.Linguistics.SEMANTIC_ROLE.BENEFICIARY
roboy.linguistics.Linguistics.SEMANTIC_ROLE.PURPOSE
roboy.linguistics.Linguistics.SEMANTIC_ROLE.CAUSE

class
    Semantic parser class.

    Connects DM to Roboy parser and adds its result to interpretation class.
```

## Public Functions

```
roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.SemanticParserAnalyzer(int p)
    A constructor.

    Creates ParserAnalyzer class and connects the parser to DM using a socket.

Interpretation roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.analyze(Interpretation i)
    An analyzer function.

    Sends input sentence to the parser and saves its response in output interpretation.

Return Input interpretation with semantic parser result.
```

### Parameters

- **interpretation:** Input interpretation with currently processed sentence and results from previous analysis.

## Private Members

```
Socket roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.clientSocket
    Client socket for the parser.

PrintWriter roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.out
    Output stream for the parser.

BufferedReader roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.in
    Input stream from the parser.

boolean roboy.linguistics.sentenceanalysis.SemanticParserAnalyzer.debug = true
    Boolean variable for debugging purpose.

enum roboy::linguistics::LinguisticsSENTENCE_TYPE
```

## Public Members

```
roboy.linguistics.Linguistics.SENTENCE_TYPE.GREETING
roboy.linguistics.Linguistics.SENTENCE_TYPE.FAREWELL
roboy.linguistics.Linguistics.SENTENCE_TYPE.SEGUE
roboy.linguistics.Linguistics.SENTENCE_TYPE.ANECDOTE
roboy.linguistics.Linguistics.SENTENCE_TYPE.WHO
```

```

roboy.linguistics.Linguistics.SENTENCE_TYPE.HOW_IS
roboy.linguistics.Linguistics.SENTENCE_TYPE.HOW_DO
roboy.linguistics.Linguistics.SENTENCE_TYPE.WHY
roboy.linguistics.Linguistics.SENTENCE_TYPE.WHEN
roboy.linguistics.Linguistics.SENTENCE_TYPE.WHERE
roboy.linguistics.Linguistics.SENTENCE_TYPE.WHAT
roboy.linguistics.Linguistics.SENTENCE_TYPE.IS_IT
roboy.linguistics.Linguistics.SENTENCE_TYPE.DOES_IT
roboy.linguistics.Linguistics.SENTENCE_TYPE.STATEMENT
roboy.linguistics.Linguistics.SENTENCE_TYPE.NONE

class

```

Tries to find triples with rather stupid heuristics and stores the results in the *Linguistics.TRIPLE* attribute of the interpretation.

## Public Functions

```

roboy.linguistics.sentenceanalysis.SentenceAnalyzer.SentenceAnalyzer()
Interpretation roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyze(Interpretat

```

## Private Functions

```

Interpretation roboy.linguistics.sentenceanalysis.SentenceAnalyzer.extractPAS(String s
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeStatement(String[] t
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeIsIt(String[] tokens,
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeDoesIt(String[] token
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeWho(String[] tokens,
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeWhat(String[] tokens,
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeHowIs(String[] token
Triple roboy.linguistics.sentenceanalysis.SentenceAnalyzer.analyzeHowDo(String[] token

```

## Private Members

```

Map<String, String> roboy.linguistics.sentenceanalysis.SentenceAnalyzer.meanings
class
Action used to shut down Roboy.

Sending a ShutdownAction leads the dialog manager to leave the communication loop in the DialogManager class and quit the program after uttering the given last words.

```

## Public Functions

```
roboy.dialog.action.ShutDownAction.ShutDownAction(List< Action > lastwords)
Constructor.
```

### Parameters

- lastwords: The last actions that Roboy should perform before shutting down

```
List<Action> roboy.dialog.action.ShutDownAction.getLastWords()
```

## Private Members

```
List<Action> roboy.dialog.action.ShutDownAction.lastwords
```

### class

Tokenizes the text by splitting at whitespace and stores the resulting tokens in the *Linguistics.TOKENS* attribute of the interpretation.

## Public Functions

```
Interpretation roboy.linguistics.sentenceanalysis.SimpleTokenizer.analyze(Interpretation
```

## Private Functions

```
String [] roboy.linguistics.sentenceanalysis.SimpleTokenizer.tokenize(String sentence)
```

### class

Currently, Roboys main personality.

It tries to engage with people in a general small talk, remembers what was said and answers questions. The small talk personality is based on a state machine, where each input is interpreted in the context of the state Roboy is currently in to determine respective answers.

The current state machine looks like this:

Greeting state | V Introduction state | V Question Randomizer state |\_Question Answering state |\_Segue state |\_Wild talk state

The Question Randomizer, Question Answering, Segue and Wilk talk states are stacked. If one cannot give an appropriate reaction to the given utterance, the utterance is passed on to the next one. The Wild talk state will always answer.

If a farewell is uttered the personality re-initializes to the Greeting state.

What the states do: Greeting: Utters a greeting Introduction: Introduces himself and asks for the others name. Reacts differently depending on whether the other person is known. Question Randomizer: Asks the other one questions about himself and stores the answers in Roboy's memory. Question Answering: Answers questions if they are asked and Roboy knows the answer. Segue: Tells anecdotes from Today-I-Learns from Reddit if corresponding keywords are mentioned. Wild talk: Talks according to a neural network model trained on chat logs.

## Public Functions

```
roboy.dialog.personality.SmallTalkPersonality.SmallTalkPersonality(Verbalizer verbalizer)
List<Action> roboy.dialog.personality.SmallTalkPersonality.answer(Interpretation input)
    Reacts to inputs based on the corresponding state Roboy is in.

Each state returns a reaction to what was said and then proactively takes an action of its own. Both are combined to return the list of output actions.

String roboy.dialog.personality.SmallTalkPersonality.getName()
void roboy.dialog.personality.SmallTalkPersonality.setName(String name)
```

## Private Functions

```
void roboy.dialog.personality.SmallTalkPersonality.initialize()
```

## Private Members

```
String roboy.dialog.personality.SmallTalkPersonality.name
State roboy.dialog.personality.SmallTalkPersonality.state
Verbalizer roboy.dialog.personality.SmallTalkPersonality.verbalizer
RosMainNode roboy.dialog.personality.SmallTalkPersonality.rosMainNode
Interlocutor roboy.dialog.personality.SmallTalkPersonality.person
```

## Private Static Attributes

Arrays.asList("enthusiastic", "awesome", "great", "very good", "dope", "smashing", "happy", "cheerful", "good", "phantastic") ]

### class

A phonetic encoder using the method soundex that maps words to their phonetic base form so that words that are written differently but sound similar receive the same form.

This is intended to be used to correct terms that Roboy misunderstood, but currently is not in use.

## Public Functions

```
roboy.linguistics.phonetics.SoundexEncoder.SoundexEncoder(Soundex soundex)
String roboy.linguistics.phonetics.SoundexEncoder.encode(String input)
```

## Private Members

```
Soundex roboy.linguistics.phonetics.SoundexEncoder.soundex
```

### class

*Action* used for talking.

## Public Functions

```
roboy.dialog.action.SpeechAction.SpeechAction(String text)  
Constructor.
```

### Parameters

- text: The text Roboy will utter

```
String roboy.dialog.action.SpeechAction.getText()
```

## Private Members

```
String roboy.dialog.action.SpeechAction.text
```

```
interface roboy::dialog::personality::statesState
```

The central interface of the state machine.

A state always acts when its enters and reacts when its left. Both, the reaction of the last and the action of the next state, are combined to give the answer of Roboy.

Subclassed by *roboy.dialog.personality.states.AbstractBooleanState*, *roboy.dialog.personality.states.AnecdoteState*, *roboy.dialog.personality.states.CelebrityState*, *roboy.dialog.personality.states.FarewellState*, *roboy.dialog.personality.states.QuestionAnsweringState*, *roboy.dialog.personality.states.QuestionAskingState*, *roboy.dialog.personality.states.QuestionRandomizerState*, *roboy.dialog.personality.states.SegueState*, *roboy.dialog.personality.states.WildTalkState*

## Public Functions

```
List<Interpretation> roboy.dialog.personality.states.State.act()
```

```
Reaction roboy.dialog.personality.states.State.react(Interpretation input)
```

```
class roboy::newDialog::statesState
```

Central class of the dialog state system.

Every dialog state should extend this class. A state always acts when it is entered and reacts when its left. Both, the reaction of the last and the action of the next state, are combined to give the answer of Roboy.

A state can have any number of transitions to other states. Every transition has a name (like “next” or “errorState”). When designing a new state, only the transition names are known. At run time the transitions will point to other states. You can get the attached state by the transition name using `getTransition(transitionName)`.

A fallback can be attached to a state. In the case this state doesn’t know how to react to an utterance, it can return null from the `react()` function. The state machine will query the fallback in this case. More details on the fallback concept can be found in the description of the `StateBasedPersonality` and in comments below.

Subclassed by *roboy.newDialog.states.toyStates.ToyFarewellState*, *roboy.newDialog.states.toyStates.ToyGreetingsState*, *roboy.newDialog.states.toyStates.ToyIntroState*, *roboy.newDialog.states.toyStates.ToyRandomAnswerState*

## Public Functions

```
roboy.newDialog.states.State.State(String stateIdentifier)
```

```
String roboy.newDialog.states.State.Identifier()
```

```
void roboy.newDialog.states.State.setIdentifier(String stateIdentifier)
```

---

```
final State roboy.newDialog.states.State.getFallback()
```

If this state can't react to the input, the Personality state machine will ask the fallback state to react to the input.

This state still remains active.

**Return** fallback state

```
final void roboy.newDialog.states.State.setFallback(State fallback)
```

Set the fallback state.

The Personality state machine will ask the fallback state if this one has no answer.

#### Parameters

- `fallback`: fallback state

```
final void roboy.newDialog.states.State.setTransition(String name, State goToState)
```

Define a possible transition from this state to another.

Something like: “next” -> {GreetingState} “rudeInput” -> {EvilState} The next active state will be selected in `getNextState()` based on internal conditions.

#### Parameters

- `name`: name of the transition
- `goToState`: state to transit to

```
final State roboy.newDialog.states.State.getTransition(String name)
```

```
final HashMap<String, State> roboy.newDialog.states.State.getAllTransitions()
```

```
abstract List<Interpretation> roboy.newDialog.states.State.act()
```

A state always acts after the reaction.

Both, the reaction of the last and the action of the next state, are combined to give the answer of Roboy.

**Return** interpretations

```
abstract List<Interpretation> roboy.newDialog.states.State.react(Interpretation input)
```

Defines how to react to an input.

This is usually the answer to the incoming question or some other statement. If this state can't react, it can return ‘null’ to trigger the fallback state for the answer.

Note: In the new architecture, `react()` does not define the next state anymore! Reaction and state transitions are now decoupled. `State` transitions are defined in `getNextState()`

**Return** reaction to the input OR null (will trigger the fallback state)

#### Parameters

- `input`: input from the person we talk to

```
abstract State roboy.newDialog.states.State.getNextState()
```

After this state has reacted, the personality state machine will ask this state to which state to go next.

If this state is not ready, it will return itself. Otherwise, depending on internal conditions, this state will select one of the states defined in transitions to be the next one.

**Return** next active state after this one has reacted

```
final boolean roboy.newDialog.states.State.allRequiredTransitionsAreInitialized()  
Checks if all required transitions were initialized correctly.
```

Required transitions are defined in `getRequiredTransitionNames()`.

**Return** true if this state was initialized correctly

```
JSONObject roboy.newDialog.states.State.toJsonObject()
```

```
String roboy.newDialog.states.State.toString()
```

```
boolean roboy.newDialog.states.State.equals(Object obj)
```

### Protected Functions

```
Set<String> roboy.newDialog.states.State.getRequiredTransitionNames()
```

Defines the names of all transition that HAVE to be defined for this state.

This function is used by `allRequiredTransitionsAreInitialized()` to make sure this state was initialized correctly. Default implementation requires no transitions to be defined.

Override this function in sub classes.

**Return** a set of transition names that have to be defined

```
Set<String> roboy.newDialog.states.State.newSet(String... tNames)
```

Utility function to create and initialize string sets in just one code line.

**Return** set initialized with inputs

#### Parameters

- `tNames`: names of the required transitions

### Private Functions

```
boolean roboy.newDialog.states.State.equalsHelper_compareTransitions(State other)  
check if every transition of this is present in the other and points to the same ID
```

**Return** true if all transitions of this state are present in the other state

#### Parameters

- `other`: other state to compare transitions

### Private Members

```
String roboy.newDialog.states.State.stateIdentifier
```

```
State roboy.newDialog.states.State.fallback
```

```
HashMap<String, State> roboy.newDialog.states.State.transitions
```

### class

Implementation of Personality based on a `DialogStateMachine`.

In contrast to previous Personality implementations, this one is more generic as it loads the dialog from a file. Additionally, it is still possible to define the dialog structure directly from code (as it was done in previous implementations).

Instead of using nested states that will pass an utterance to each other if a state cannot give an appropriate reaction, we use a fallback concept. If a state doesn't know how to react, it simply doesn't react at all. If a fallback (with is another state) is attached to it, the personality will pass the utterance to the fallback automatically. This concept helps to decouple the states and reduce the dependencies between them.

## Public Functions

`roboy.newDialog.StateBasedPersonality.StateBasedPersonality(Verbalizer verb)`

`List<Action> roboy.newDialog.StateBasedPersonality.startConversation()`

Always called once by the (new) DialogSystem at the beginning of every new conversation.

**Return** list of actions based on act() of the initial/active state

`List<Action> roboy.newDialog.StateBasedPersonality.answer(Interpretation input)`

The central method of a personality.

Given an interpretation of all inputs (audio, visual, ...) to Roboy, this method decides which actions to perform in response.

**Return** A list of actions to perform in response

### Parameters

- `input`: The interpretation of the inputs

## Private Functions

`void roboy.newDialog.StateBasedPersonality.reset()`

`List<Action> roboy.newDialog.StateBasedPersonality.stateAct(State state)`

Call the act function of the state and verbalize all interpretations into actions.

**Return** list of actions

### Parameters

- `state`: state to call ACT on

`List<Action> roboy.newDialog.StateBasedPersonality.stateReact(State state, Interpretation input)`

Call the react function of the state.

If the state can't react, recursively ask fallbacks. Verbalize the resulting reaction interpretation into actions.

**Return** list of actions

### Parameters

- `state`: state to call REact on
- `input`: input from the person Roboy speaks to

`List<Action> roboy.newDialog.StateBasedPersonality.verbalizeInterpretations(List< Interpretation> interpretations)`

Verbalizes all interpretations into actions using the verbalizer.

**Return** list of actions

### Parameters

- `interpretations`: list of interpretations.

### Private Members

```
final Verbalizer roboy.newDialog.StateBasedPersonality.verbalizer  
class roboy::newDialog::examplesStateMachineExamples
```

This class provides examples how to load state machines from files or create them from code directly.

### Public Static Functions

```
static void roboy.newDialog.examples.StateMachineExamples.main(String[] args)
```

### Private Static Functions

```
static DialogStateMachine roboy.newDialog.examples.StateMachineExamples.fromCode()  
static DialogStateMachine roboy.newDialog.examples.StateMachineExamples.fromFile()  
static DialogStateMachine roboy.newDialog.examples.StateMachineExamples.fromString()
```

### Private Static Attributes

```
final String roboy.newDialog.examples.StateMachineExamples.toyPersonality  
class roboy::talkStatementBuilder
```

### Public Static Functions

```
static String roboy.talk.StatementBuilder.random(List< String > list)  
Returns a random element from the given list of Strings.
```

#### Return

#### Parameters

- list:

```
class roboy::logicStatementInterpreter
```

### Public Static Functions

```
static boolean roboy.logic.StatementInterpreter.isFromList(String input, List< String > list)  
Checks if the given String contains one of the Strings from the given list.
```

#### Return

#### Parameters

- input:
- list:

```
class roboy::linguisticsTerm
```

## Public Functions

```
String roboy.linguistics.Term.toString()
```

## Public Members

```
List<String> roboy.linguistics.Term.pos
```

```
float roboy.linguistics.Term.prob
```

```
String roboy.linguistics.Term.concept
```

```
class roboy::linguistics::word2vec::examplesToyDataGetter
```

Utility class to load toy data from the internet if necessary.

May be refactored into something bigger and more useful later.

## Public Functions

```
roboy.linguistics.word2vec.examples.ToyDataGetter.ToyDataGetter(boolean verbose)
```

```
String roboy.linguistics.word2vec.examples.ToyDataGetter.getToyDataFilePath()
```

```
void roboy.linguistics.word2vec.examples.ToyDataGetter.ensureToyDataIsPresent()
```

Checks if toy data is present on the hard drive.

It will be downloaded if necessary.

## Private Functions

```
void roboy.linguistics.word2vec.examples.ToyDataGetter.downloadData(String fromURL, String toFile)
```

```
boolean roboy.linguistics.word2vec.examples.ToyDataGetter.fileExists(String filePath)
```

## Private Members

```
final boolean roboy.linguistics.word2vec.examples.ToyDataGetter.verbose
```

```
final String roboy.linguistics.word2vec.examples.ToyDataGetter.toyDataDirectory = "./resources/todata"
```

```
final String roboy.linguistics.word2vec.examples.ToyDataGetter.toyDataFilePath = "./resources/todata/words.txt"
```

```
final String roboy.linguistics.word2vec.examples.ToyDataGetter.toyDataInetURL = "https://raw.githubusercontent.com/roboy-project/roboy-languistics/master/resources/todata/words.txt"
```

```
class
```

*ToyFarewellState* always acts with “Bye bye”.

The Interlocutor answer is ignored and there is no reaction. This ends the conversation.

Fallback is not required. This state has no outgoing transitions.

## Public Functions

```
roboy.newDialog.states.toyStates.ToyFarewellState.ToyFarewellState(String stateIdentifier)
List<Interpretation> roboy.newDialog.states.toyStates.ToyFarewellState.act()
List<Interpretation> roboy.newDialog.states.toyStates.ToyFarewellState.react(Interpretation)
State roboy.newDialog.states.toyStates.ToyFarewellState.getNextState()
```

**class**

*ToyGreetingsState* can be used as the initial state.

Roboy will greet the Interlocutor with “Hello”.

If the response is a greeting, the “next” transition is taken. Otherwise the fallback will be triggered and the “noHello” transition is taken.

Fallback is required. Outgoing transitions that have to be defined:

- next: following state if there was a greeting
- noHello: following state if there was NO greeting

## Public Functions

```
roboy.newDialog.states.toyStates.ToyGreetingsState.ToyGreetingsState(String stateIdentifier)
List<Interpretation> roboy.newDialog.states.toyStates.ToyGreetingsState.act()
List<Interpretation> roboy.newDialog.states.toyStates.ToyGreetingsState.react(Interpretation)
State roboy.newDialog.states.toyStates.ToyGreetingsState.getNextState()
```

## Protected Functions

```
Set<String> roboy.newDialog.states.toyStates.ToyGreetingsState.getRequiredTransitionNames()
```

## Private Members

```
boolean roboy.newDialog.states.toyStates.ToyGreetingsState.inputOK = true
```

**class**

*ToyIntroState* demonstrates a simple introduction.

Roboy will tell the Interlocutor his name and ask for the Interlocutor’s name. The reply is ignored.

Fallback is not required. Outgoing transitions that have to be defined:

- next: following state

## Public Functions

```
roboy.newDialog.states.toyStates.ToyIntroState.ToyIntroState(String stateIdentifier)
List<Interpretation> roboy.newDialog.states.toyStates.ToyIntroState.act()
List<Interpretation> roboy.newDialog.states.toyStates.ToyIntroState.react(Interpretation)
```

---

```
State roboy.newDialog.states.toyStates.ToyIntroState.getNextState()
```

### Protected Functions

```
Set<String> roboy.newDialog.states.toyStates.ToyIntroState.getRequiredTransitionNames()
class
```

*ToyRandomAnswerState* is meant to be used as a fallback state.

It only implements the react() function returning a hardcoded random answer. This state should never become active (meaning that no transition should point to it.)

Fallback is not required (this state should be the fallback). This state has no outgoing transitions.

### Public Functions

```
roboy.newDialog.states.toyStates.ToyRandomAnswerState.ToyRandomAnswerState(String state)
```

```
List<Interpretation> roboy.newDialog.states.toyStates.ToyRandomAnswerState.act()
```

```
List<Interpretation> roboy.newDialog.states.toyStates.ToyRandomAnswerState.react(Interpre
```

```
State roboy.newDialog.states.toyStates.ToyRandomAnswerState.getNextState()
```

```
class roboy::newDialog::states::factories::ToyStateFactory
```

Temporary factory to create *State* objects based on class name.

May be replaced with something more generic later.

### Public Static Functions

```
static State roboy.newDialog.states.factories.ToyStateFactory.getByClassName(String cl
```

```
class roboy::linguistics::Triple
```

Represents a simple who(agents) does what(predicate) to whom(patiens) relation.

### Public Functions

```
roboy.linguistics.Triple.Triple(String predicate, String agents, String patiens)
```

```
String roboy.linguistics.Triple.toString()
```

### Public Members

```
String roboy.linguistics.Triple.agents
```

```
String roboy.linguistics.Triple.predicate
```

```
String roboy.linguistics.Triple.patiens
```

```
class
```

Created by roboy on 7/27/17.

## Public Functions

```
roboy.io.UdpInput.UdpInput(DatagramSocket ds)
Input roboy.io.UdpInput.listen()
```

## Private Members

```
DatagramSocket roboy.io.UdpInput.serverSocket
class
Created by roboy on 7/27/17.
```

## Public Functions

```
roboy.io.UdpOutput.UdpOutput(DatagramSocket ds, String address, int port)
void roboy.io.UdpOutput.act(List< Action > actions)
```

## Private Members

```
DatagramSocket roboy.io.UdpOutput.serverSocket
InetAddress roboy.io.UdpOutput.udpEndpointAddress
int roboy.io.UdpOutput.updEndpointPort
enum roboy::context::ContextUpdaters
All available updaters by their class and their target's value type.
```

## Public Functions

```
roboy.context.Context.Updaters.Updaters(Class attribute, Class valueType)
```

## Public Members

```
roboy.context.Context.Updaters.DIALOG_TOPICS_UPDATER=(DialogTopicsUpdater.class, String.class)
final Class roboy.context.Context.Updaters.classType
final Class roboy.context.Context.Updaters.targetValueType
class roboy::memoryUtil : public Exception
Helper class.
```

## Public Static Functions

```
static String roboy.memory.Util.getPartURI(String URI)
static List<String> roboy.memory.Util.getQuestionType(String question)
static int roboy.memory.Util.calculateLevenshteinDistance(String s, String t)
static int roboy.memory.Util.min(int a, int b, int c)
```

```
template <V>
class roboy::context::Value : public roboy::context::AbstractValue<V>
    Stores a single value of type V.
    Subclassed by roboy.context.contextObjects.FaceCoordinates
```

### Public Functions

```
V roboy.context.Value< V >.getValue()
void roboy.context.Value< V >.updateValue(V value)
```

### Private Members

```
volatile V roboy.context.Value< V >.value = null
enum roboy::context::ContextValueHistories
    All available valueHistories.
```

### Public Functions

```
roboy.context.Context.ValueHistories.ValueHistories(Class<?extends AbstractValueHisto
Class roboy.context.Context.ValueHistories.getClassType()
Class roboy.context.Context.ValueHistories.getReturnType()
public<T> T roboy.context.Context.ValueHistories.getLastValue()
public<K, T> Map<K, T> roboy.context.Context.ValueHistories.getNLastValues(int n)
```

### Public Members

```
roboy.context.Context.ValueHistories.DIALOG_TOPICS =(DialogTopics.class, String.class)
final Class roboy.context.Context.ValueHistories.classType
final Class roboy.context.Context.ValueHistories.returnType

template <V>
class
    HashMap implementation of a value history with unique Integer keys.
    Subclassed by roboy.context.contextObjects.DialogTopics
```

### Public Functions

```
roboy.context.ValueHistory< V >.ValueHistory()
V roboy.context.ValueHistory< V >.getValue()
```

Return

The last element added to this list.

```
HashMap<Integer, V> roboy.context.ValueHistory< V >.getLastNValues(int n)
```

Get a copy of the last n entries added to the list.

Less values may be returned if there are not enough values in this list. In case of no values, an empty array is returned.

**Return** A hashmap of n last values added to the list.

#### Parameters

- n: The number of instances to retrieve.

```
synchronized void roboy.context.ValueHistory< V >.updateValue(V value)
```

Puts a value into the list in the last place.

#### Parameters

- value: The value to be added.

### Private Functions

```
synchronized int roboy.context.ValueHistory< V >.generateKey()
```

Generates a key that is unique through incrementing an internal counter.

**Return** A key which is unique in this list instance.

```
synchronized V roboy.context.ValueHistory< V >.getValue(int key)
```

In a ValueList, only `getValue()` and `updateValue()` directly access the HashMap data.

Setting these methods to be synchronous avoids concurrency issues.

**Return** The value, or `null` if not found.

#### Parameters

- key: The key of the value.

### Private Members

```
volatile int roboy.context.ValueHistory< V >.counter
```

This counter tracks the number of values, indices still start from 0.

Reading is allowed without synchronization, modifications only through `generateKey()`.

```
HashMap<Integer, V> roboy.context.ValueHistory< V >.data
```

```
enum roboy::context::ContextValues
```

All available values.

### Public Functions

```
roboy.context.Context.Values.Values(Class<?extends AbstractValue > attribute, Class <?> type)
```

```
Class roboy.context.Context.Values.getClassType()
```

```
Class roboy.context.Context.Values.getReturnType()
```

```
public<T> T roboy.context.Context.Values.getLastValue()
```

## Public Members

```
roboy.context.Context.Values.FACE_COORDINATES =(FaceCoordinates.class, CoordinateSet.class)
final Class roboy.context.Context.Values.classType
final Class roboy.context.Context.Values.returnType
```

### class roboy::talkVerbalizer

Turns interpretations to actual utterances.

This should in the future lead to diversifying the ways Roboy is expressing information.

## Public Functions

### Action roboy.talk.Verbalizer.verbalize(Interpretation interpretation)

Currently contains utterance diversification for greetings, farewells, segue and introductions to anecdotes.

In all other cases the state machine provides a literal sentence that is just passed through. In the future, this should be extended to diversify everything Roboy says.

**Return** the actual action that is performed

#### Parameters

- interpretation: the abstraction of what Roboy intends to say

## Public Static Attributes

```
Arrays.asList("hello","hi","greetings","good morning","howdy","good day","hey") ]
```

```
Arrays.asList("ciao","goodbye","cheerio","bye","see you", "farewell","bye-bye") ]
```

## Private Functions

### SpeechAction roboy.talk.Verbalizer.greet(Interpretation interpretation)

### ShutdownAction roboy.talk.Verbalizer.farewell(Interpretation interpretation)

### SpeechAction roboy.talk.Verbalizer.segue(Interpretation interpretation)

### SpeechAction roboy.talk.Verbalizer.anecdote(Interpretation interpretation)

### Interpretation roboy.talk.Verbalizer.verbalizeDates(Interpretation interpretation)

### String roboy.talk.Verbalizer.dateToText(String date)

### SpeechAction roboy.talk.Verbalizer.literalSentence(Interpretation interpretation)

## Private Static Attributes

```
Arrays.asList("talking about ","since you mentioned ","on the topic of ") ]
```

```
Arrays.asList("here is an interesting bit of trivia. "," how about this? ") ]
```

```
Arrays.asList("did you know ","did you know that ","i read that "," i heard that ","have you heard this: ")
]
```

```
final Map<String, String> roboy.talk.Verbalizer.dayNumberMap
    1,"one", 2,"two", 3,"three", 4,"four", 5,"five", 6,"six", 7,"seven", 8,"eight", 9,"nine", 10,"ten", 11,"eleven",
    12,"twelve", 13,"thirteen", 14,"fourteen", 15,"fifteen", 16,"sixteen", 17,"seventeen", 18,"eighteen",
    19,"nineteen" ) ]
    "1","January", "2","February", "3","March", "4","April", "5","May", "6","June", "7","July", "8","Au-
    gust", "9","September", "01","January", "02","February", "03","March", "04","April", "05","May",
    "06","June", "07","July", "08","August", "09","September", "10","October", "11","November",
    "12","December" ) ]
    1,"ten", 2,"twenty", 3,"thirty", 4,"forty", 5,"fifty", 6,"sixty", 7,"seventy", 8,"eighty", 9,"ninety" ) ]
class roboy::talkVerbalizerTest
```

### Public Functions

```
void roboy.talk.VerbalizerTest.testDates()
class roboy::ioVision
    Vision helper class.
```

### Public Functions

```
String roboy.io.Vision.recognizeFace()
boolean roboy.io.Vision.findFaces()
```

### Public Static Functions

```
static Vision roboy.io.Vision.getInstance()
```

### Private Functions

```
roboy.io.Vision.Vision()
```

### Private Static Attributes

```
Vision roboy.io.Vision.roboyVision
class roboy::io::VisionVisionCallback : public TopicCallback
```

### Public Functions

```
void roboy.io.Vision.VisionCallback.handleMessage(Message message)
```

## Public Members

```
String roboy.io.Vision.VisionCallback.latest = null
boolean roboy.io.Vision.VisionCallback.faceDetected = false
class
The generative model talking wildly.
```

## Public Functions

```
roboy.dialog.personality.states.WildTalkState.WildTalkState(RosMainNode node)
List<Interpretation> roboy.dialog.personality.states.WildTalkState.act()
Reaction roboy.dialog.personality.states.WildTalkState.react(Interpretation input)
void roboy.dialog.personality.states.WildTalkState.setNextState(State next)
```

## Private Members

```
State roboy.dialog.personality.states.WildTalkState.next = this
RosMainNode roboy.dialog.personality.states.WildTalkState.rosMainNode
class roboy::linguistics::word2vec::examplesWord2vecTrainingExample
Neural net that processes text into word-vectors.

Adapted from org.deeplearning4j.examples.nlp.word2vec.Word2VecRawTextExample
```

## Public Static Functions

```
static void roboy.linguistics.word2vec.examples.Word2vecTrainingExample.main(String[])
class roboy::linguistics::word2vec::examplesWord2vecUptrainingExample
Neural net that processes text into word-vectors.

This example shows how to save/load and train the model.

Adapted from org.deeplearning4j.examples.nlp.word2vec.Word2VecUptrainingExample
```

## Public Static Functions

```
static void roboy.linguistics.word2vec.examples.Word2vecUptrainingExample.main(String[])
class
```

## Public Functions

```
boolean roboy.memory.WorkingMemory.save(Triple object)
String roboy.memory.WorkingMemory.toString()
List<Triple> roboy.memory.WorkingMemory.retrieve(Triple object)
```

### Public Static Functions

```
static WorkingMemory roboy.memory.WorkingMemory.getInstance()
```

### Private Functions

```
roboy.memory.WorkingMemory.WorkingMemory()
```

```
void roboy.memory.WorkingMemory.addToMap(Map< String, List< Triple >> list, String s
```

### Private Members

```
Map<String, List<Triple> > roboy.memory.WorkingMemory.agensTripleMap = new HashMap<>()
```

```
Map<String, List<Triple> > roboy.memory.WorkingMemory.patientsTripleMap = new HashMap<>()
```

```
Map<String, List<Triple> > roboy.memory.WorkingMemory.predicateTripleMap = new HashMap<>()
```

### Private Static Attributes

```
WorkingMemory roboy.memory.WorkingMemory.memory  
namespace com::googlejson  
namespace edu::cmu::sphinxapi  
namespace javaawt  
namespace javaio  
namespace javanet  
namespace javautil  
namespace javaxswing  
namespace org::apache::jenaquery  
namespace org::apache::jena::rdfmodel  
namespace org::apache::jenasparql  
namespace org::junitAssert  
namespace org::rosnode  
namespace roboy  
namespace roboycontext  
namespace roboy::contextcontextObjects  
namespace roboy::contextGUI  
namespace roboy::contextvisionContext  
namespace roboydialog  
namespace roboy::dialogaction  
namespace roboy::dialog::ConfigConfigurationProfile  
namespace roboy::dialogpersonality
```

```
namespace roboy::dialog::personalitystates
namespace roboyio
namespace roboylinguistics
namespace roboy::linguisticsphonetics
namespace roboy::linguisticssentenceanalysis
namespace roboy::linguisticsword2vec
namespace roboy::linguistics::word2vecexamples
namespace roboylogic
namespace roboymemory
namespace roboy::memoryNeo4jRelationships
namespace roboy::memorynodes
namespace roboynewDialog
namespace roboy::newDialogexamples
namespace roboy::newDialogstates
namespace roboy::newDialog::statesfactories
namespace roboy::newDialog::statestoyStates
namespace roboyros
namespace roboytalk
namespace roboyutil
namespace roboy_communication_cognition
namespace roboy_communication_control
file AbstractValue.java
file AbstractValueHistory.java
file AttributeManager.java
file Context.java
file CoordinateSet.java
file DialogTopics.java
file DialogTopicsUpdater.java
file FaceCoordinates.java
file FaceCoordinatesUpdater.java
file ExternalContextInterface.java
file ExternalUpdater.java
file ContextGUI.java
file InternalUpdater.java
file IntervalUpdater.java
file Value.java
```

```
file ValueHistory.java  
file Action.java  
file FaceAction.java  
file ShutDownAction.java  
file SpeechAction.java  
file Config.java  
file DialogSystem.java  
file CuriousPersonality.java  
file DefaultPersonality.java  
file KnockKnockPersonality.java  
file Personality.java  
file SmallTalkPersonality.java  
file AbstractBooleanState.java  
file AnecdoteState.java  
file CelebrityState.java  
file ConverseState.java  
file FarewellState.java  
file GenerativeCommunicationState.java  
file GreetingState.java  
file IdleState.java  
file InquiryState.java  
file IntroductionState.java  
file LocationDBpedia.java  
file PersonalFollowUpState.java  
file PersonalQAState.java  
file QuestionAnsweringState.java  
file QuestionAskingState.java  
file QuestionRandomizerState.java  
file Reaction.java  
file SegueState.java  
file State.java  
file State.java  
file WildTalkState.java  
file BingInput.java  
file BingOutput.java  
file CelebritySimilarityInput.java
```

*file CerevoiceOutput.java*  
*file CommandLineCommunication.java*  
*file CommandLineInput.java*  
*file CommandLineOutput.java*  
*file Communication.java*  
*file EmotionOutput.java*  
*file FreeTTSOutput.java*  
*file Input.java*  
*file InputDevice.java*  
*file MultiInputDevice.java*  
*file MultiOutputDevice.java*  
*file OutputDevice.java*  
*file RoboyNameDetectionInput.java*  
*file UdpInput.java*  
*file UdpOutput.java*  
*file Vision.java*  
*file Concept.java*  
*file Concept.java*  
*file DetectedEntity.java*  
*file Entity.java*  
*file Linguistics.java*  
*file DoubleMetaphoneEncoder.java*  
*file MetaphoneEncoder.java*  
*file PhoneticEncoder.java*  
*file Phonetics.java*  
*file SoundexEncoder.java*  
*file Analyzer.java*  
*file AnswerAnalyzer.java*  
*file DictionaryBasedSentenceTypeDetector.java*  
*file EmotionAnalyzer.java*  
*file IntentAnalyzer.java*  
*file Interpretation.java*  
*file OntologyNERAnalyzer.java*  
*file OpenNLPParser.java*  
*file OpenNLPPPOSTagger.java*  
*file Preprocessor.java*

```
file SemanticParserAnalyzer.java
file SentenceAnalyzer.java
file SimpleTokenizer.java
file Term.java
file Triple.java
file ToyDataGetter.java
file Word2vecTrainingExample.java
file Word2vecUptrainingExample.java
file Intention.java
file IntentionClassifier.java
file PASInterpreter.java
file StatementInterpreter.java
file DBpediaMemory.java
file Lexicon.java
file LexiconLiteral.java
file LexiconPredicate.java
file Memory.java
file Neo4jMemory.java
file Neo4jRelationships.java
file Interlocutor.java
file MemoryNodeModel.java
file Roboy.java
file PersistentKnowledge.java
file RoboyMind.java
file Util.java
file WorkingMemory.java
file DialogStateMachine.java
file StateMachineExamples.java
file NewDialogSystem.java
file StateBasedPersonality.java
file ToyStateFactory.java
file ToyFarewellState.java
file ToyGreetingsState.java
file ToyIntroState.java
file ToyRandomAnswerState.java
file Ros.java
```



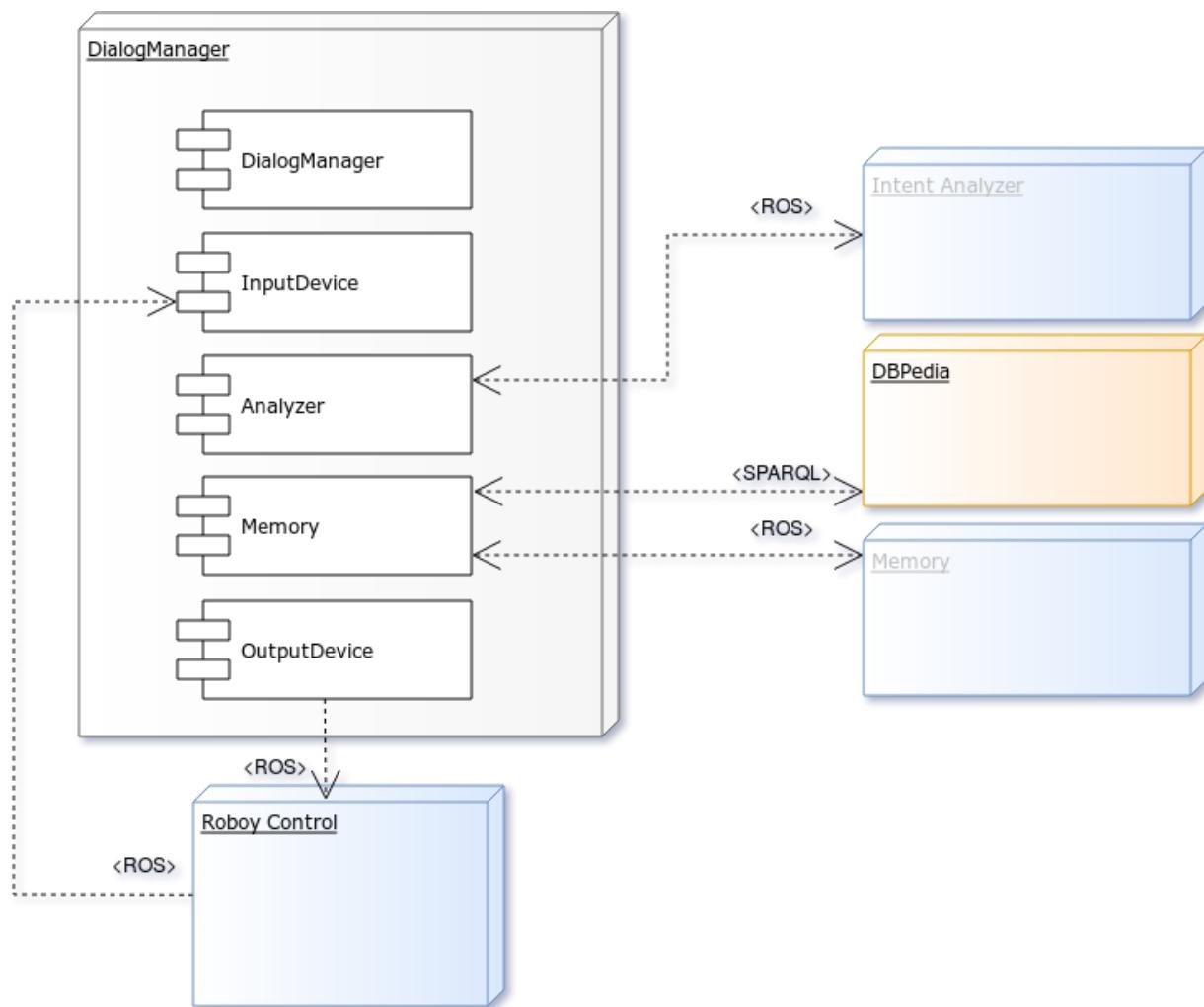
## 2.9 Deployment diagram

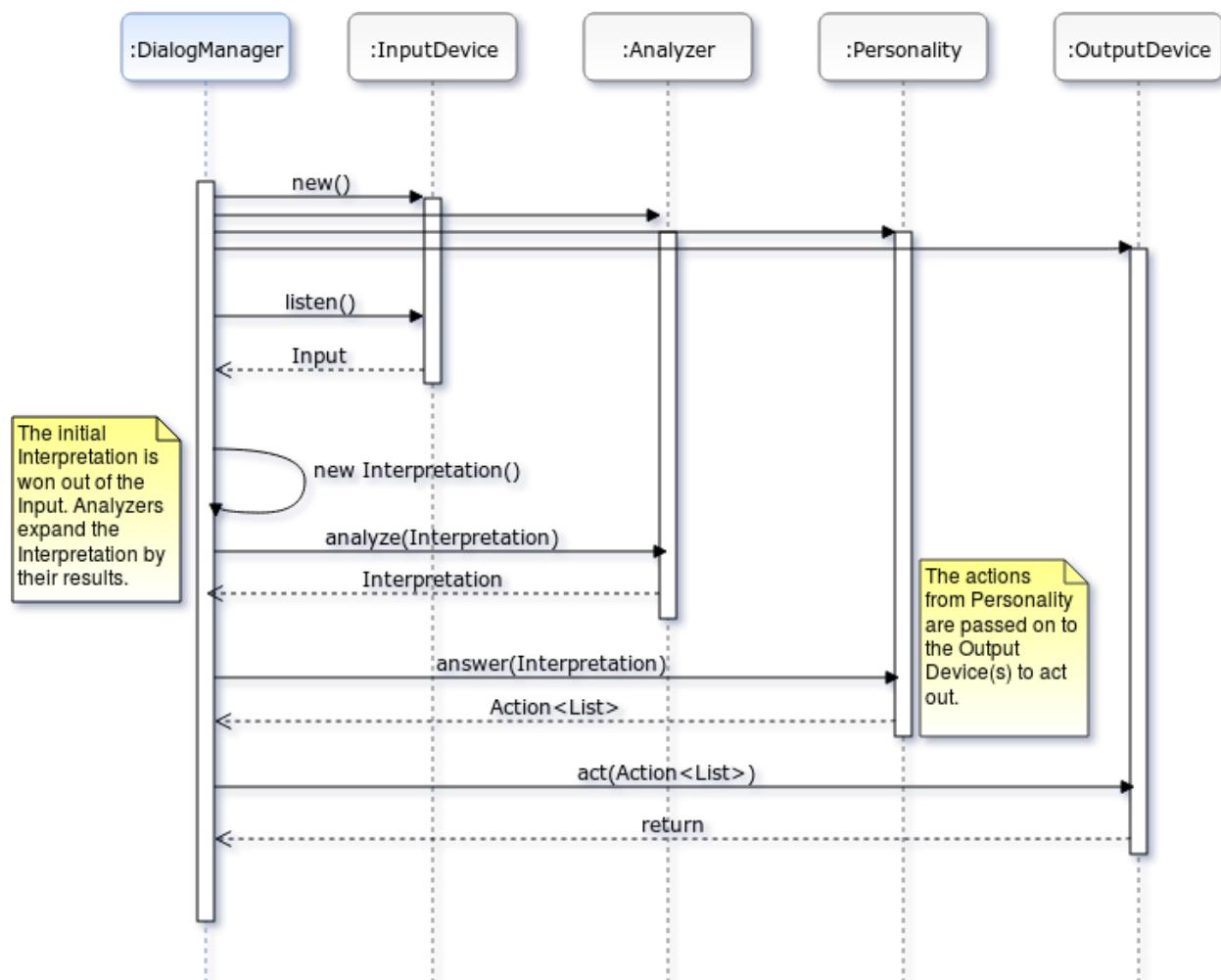
This diagram depicts the external modules and their communication channels/protocols with the Dialog Manager. Modules which are in development (intents, Memory) are included in gray. For simplicity, the Dialog Manager module only contains these components which are most relevant for external connections.

## 2.10 Sequence diagram

This is a simple high-abstraction sequence of the Dialog Manager's workflow, starting at the initialization and going from registering input over interpretation and action generation to sending output actions.

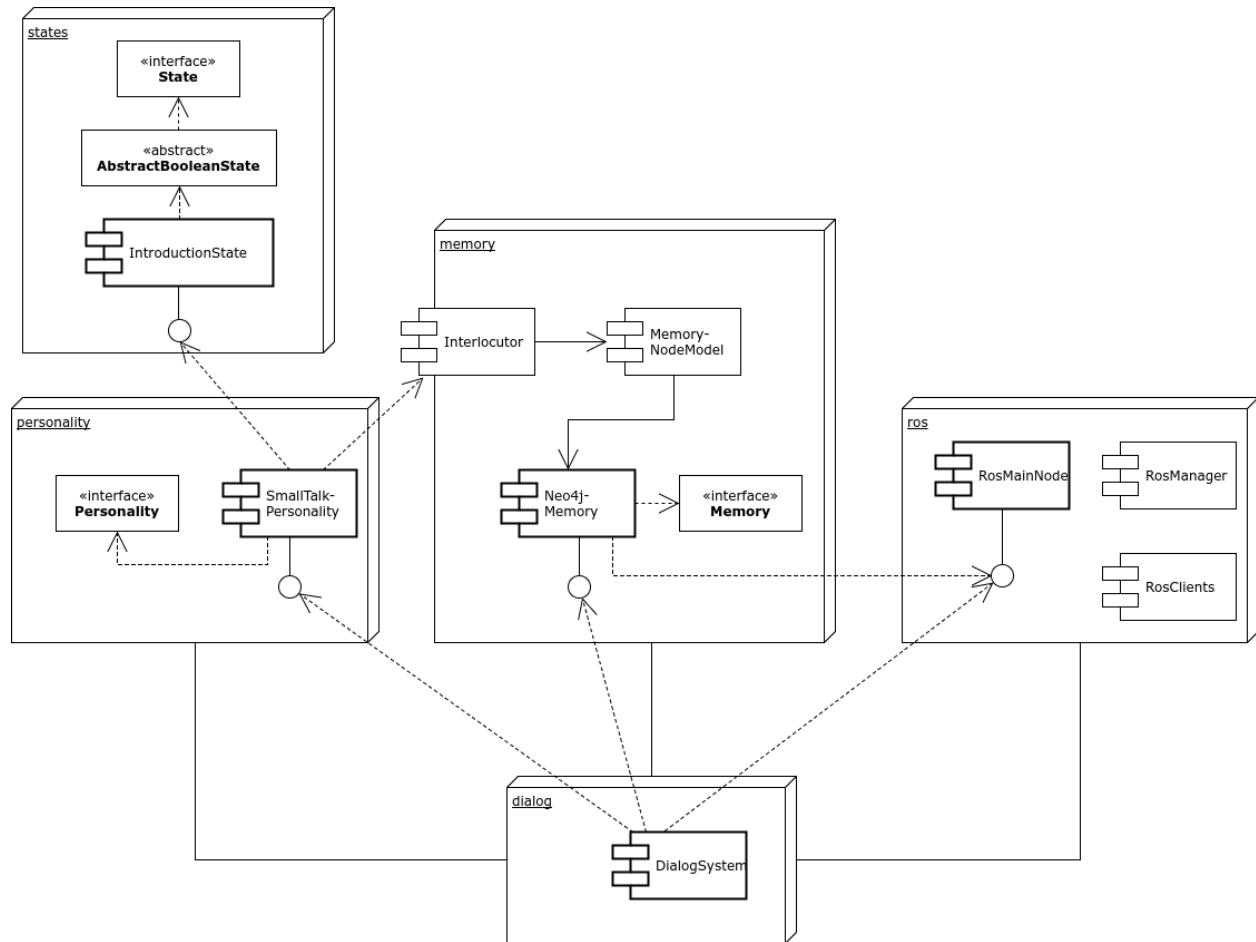
### **alt** Sequence diagram





## 2.11 Building block diagram

This diagram depicts the internal modules of the Dialog System and their dependency hierarchies.



**alt** Building block diagram

## 2.12 About arc42

This information should stay in every repository as per their license: <http://www.arc42.de/template/licence.html>  
arc42, the Template for documentation of software and system architecture.

By Dr. Gernot Starke, Dr. Peter Hruschka and contributors.

Template Revision: 6.5 EN (based on asciidoc), Juni 2014

© We acknowledge that this document uses material from the arc 42 architecture template, <http://www.arc42.de>. Created by Dr. Peter Hruschka & Dr. Gernot Starke. For additional contributors see <http://arc42.de/sonstiges/contributors.html>

### Note

This version of the template contains some help and explanations. It is used for familiarization with arc42 and the understanding of the concepts. For documentation of your own system you use better the *plain* version.

### **2.12.1 Literature and references**

**Starke-2014** Gernot Starke: Effektive Softwarearchitekturen - Ein praktischer Leitfaden. Carl Hanser Verlag, 6, Auflage 2014.

**Starke-Hruschka-2011** Gernot Starke und Peter Hruschka: Softwarearchitektur kompakt. Springer Akademischer Verlag, 2. Auflage 2011.

**Zörner-2013** Softwarearchitekturen dokumentieren und kommunizieren, Carl Hanser Verlag, 2012

### **2.12.2 Examples**

- [HTML Sanity Checker](#)
- [DocChess \(german\)](#)
- [Gradle \(german\)](#)
- [MaMa CRM \(german\)](#)
- [Financial Data Migration \(german\)](#)

### **2.12.3 Acknowledgements and collaborations**

arc42 originally envisioned by [Dr. Peter Hruschka](#) and [Dr. Gernot Starke](#).

**Sources** We maintain arc42 in *asciidoc* format at the moment, hosted in [GitHub](#) under the aim42-Organisation.

**Issues** We maintain a list of [open topics and bugs](#).

We are looking forward to your corrections and clarifications! Please fork the repository mentioned over this lines and send us a *pull request!*

### **2.12.4 Collaborators**

We are very thankful and acknowledge the support and help provided by all active and former collaborators, uncountable (anonymous) advisors, bug finders and users of this method.

#### **Currently active**

- Gernot Starke
- Stefan Zörner
- Markus Schärtel
- Ralf D. Müller
- Peter Hruschka
- Jürgen Krey

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(in alphabetical order)

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- Matthias Bohlen
- Karl Eilebrecht
- Manfred Ferken
- Phillip Ghadir
- Carsten Klein
- Prof. Arne Koschel
- Axel Scheithauer



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